



Fundamentals of Systems Engineering

Prof. Olivier L. de Weck 20 November 2015

Session 10 Commissioning and Operations

General Status Update

Assignment	Topic	Weight
A1 (group)	Team Formation, Definitions, Stakeholders, Concept of Operations (CONOPS)	12.5%
A2 (group)	Requirements Definition and Analysis Margins Allocation	12.5%
A3 (group)	System Architecture, Concept Generation	12.5%
A4 (group)	Tradespace Exploration, Concept Selection	12.5%
A5 (group)	Preliminary Design Review (PDR) Package and Presentation	20%
Quiz (individual)	Written online quiz	10%
Oral Exam (individual)	20' Oral Exam with Instructor 2-page reflective memorandum	10%

A5 is due today!

The "V-Model" of Systems Engineering

16.842/ENG-421 Fundamentals of Systems Engineering



Numbers indicate the session # in this class

Outline for Today

- Operational Considerations
- Commissioning
- Research into Operations
 - Reconfigurability and Common Sparing for Mars Missions
 - Designing Systems for Operations in Partially Failed States
- Post-Flight Review (PFR)

The question ...

Why would a small mountainous country select a U.S. Navy military aircraft originally designed for a completely different operational mission?



Image by MIT OpenCourseWare.

Answer: Superior Lifecycle Properties

- A) Flexibility (air patrol, intercept, ground attack)
- B) Maintainability (21 vs 56 DMMH/FH)
- C) Evolvability (spare capacity, e.g. in LEX)

Flight Operations



Turn-to-Partner Exercise

- What has been your experience with operations of a cyber-physical system? Did the system start-up well? What where the challenges? What would you do differently if you could do it again?
- Discuss.
- Share.

F/A-18 Fatigue Life Monitoring

International Journal of Fatigue Volume 29, Issues 9–11, September–November 2007, Pages 1647–1657 Fatigue Damage of Structural Materials VI The Sixth International Conference on Fatigue Damage of Structural Materials **Flight-by-flight fatigue crack growth life assessment**

W. Zhuang, , S. Barter, L. Molent



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Space Shuttle Lifetime Cost (1971-2011)



- Vision: partially reusable space vehicle with quick turnaround and high flight rate
- Actual: complex and fragile vehicle with average cost of about \$1.5B/flight (20,000 workforce)
- Why?
 - Overoptimism
 - Congress capped RDT&E at \$B5.15 (1971)
 - Focus on achieving launch performance (24 mt LEO)
 - Maintainability needed to be "designed-in"
 - No realistic lifecycle cost/value optimization done

What we wanted



This image is in the public domain. What we got



This image is in the public domain.

Operational Considerations

- How will the system be operated?
- What insights do the operators need into the system status?
- Before turning over to the operators what checks need to be performed?
- How might the system fail?
- What options are available to the operators in the event of system failures?!
 - What spares are needed to repair the system?
 - Will the system still perform even under partial failures?

NASA Life-Cycle Phases

NASA Life Cycle Phases	Pre-Systems	FORMUI Acquisition	ATION Appro Impler	neptatio System	IMPLE as Acquisition	MENTATION	Decommissioning
Project Life Cycle Phases	Pre-Phase A: Concept Studies	Phase A: Concept & Technology Development	Phase B: Preliminary Design & echnology Completior	Phase C: Final Design & Fabrication	Phase D: System Assembly, Int & Test, Launch	Phase E: Operations & Sustainment	Phase F: Closeout
Project Life Cycle Gates & Major Events	KDP A FAD Draft Project Requirements	KDP B Preliminary Project Plan	KDP C Baseline Project Plan ⁷	Z KDP D	Z KDP E V	KDP F End of Mission	7 Final Archival of Data
Agency Reviews	ASP ⁵	ASM ⁵					
Human Space Flight Project Reviews¹		$\sum_{R} \qquad \sum_{\substack{SRR SDR \\ (PNAR}}$	PDR (NAR)	CDR / SIR	SAR ORR FI	$ \begin{array}{c} & & \\ & & \\ & \\ & \\ & \\ & \\ & \\ & \\ & $	\sum_{DR}
Re-flights			Re-enters appropriate life modifications are needed b	cycle phase if	Refurbishment		
Robotic Mission Project Reviews ¹	Δ		\triangle	\triangle \triangle		$ \sum_{n=1}^{PPAK} $	\triangle
Launch Readiness Reviews	мс	R SRR MDR⁴ (PNAR)	PDR (NAR)	CDR / SI PRR ²	r orr	RR PLAR CERR ³ SMSR, LRR (LV), FRR (LV)	DR
Supporting Reviews		Peer Peer	Reviews, Subsyst	em PDRs, Subsyst	em CDRs, and Sys	em Reviews	\bigtriangleup
 FOOTNOTES Flexibility is allowed in the timing, number, and content of reviews as long as the equivalent information is provided at each KDP and the approach is fully documented in the Project Plan. These reviews are conducted by the project for the independent SRB. See Section 2.5 and Table 2-6. PRR needed for multiple (≥4) system copies. Timing is notional. CERRs are established at the discretion of Program Offices. For robotic missions, the SRR and the MDR may be combined. The ASP and ASM are Agency reviews, not life-cycle reviews. Includes recertification, as required. Project Plans are baselined at KDP C and are reviewed and updated as required, to ensure project content, cost, and budget remain consistent. 			ACRONYMS ASP—Acquisition Strategy Planning Meeting ASM—Acquisition Strategy Meeting CDR—Critical Design Review CERR—Critical Events Readiness Review DR—Decommissioning Review FAD—Formulation Authorization Document FRR—Flight Readiness Review KDP—Key Decision Point LRR—Launch Readiness Review MCR—Mission Concept Review MDR—Mission Definition Review SMB—System Integration Review SMR—System Review SRR—System Review SRR—System Review				

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Transitioning and Operating

Phase D

System Assembly, Integration and Test, Launch To assemble and integrate the products to create the system, meanwhile developing confidence that it will be able to meet the system requirements. Launch and prepare for operations. Perform system end product implementation, assembly, integration and test, and transition to use.

Phase E

Operations and Sustainment

To conduct the mission and meet the initially identified need and maintain support for that need. Implement the mission operations plan.

Common Technical Processes



NASA Product Transition Process



Figure 5.5-1 Product Transition Process

Pg. 106, NASA SE Handbook

This image is in the public domain.

Product Transitioning \rightarrow Commissioning

- Deploying System in the Field
 - Transition to operators (legally and physically)
 - Training of operators
- Checkout
 - Turning on all systems and subsystems
 - Comparing predicted parameters against actual behaviors
- Sustainment
 - Maintenance (preventative, corrective)
 - Spare Parts Management
 - Reconfiguring Systems during Use, Upgrades
 - Retrofits

NASA Operations Phases

Table 4.1-1 Typical Operational Phases for a NASA Mission

Operational Phase	Description
Integration and test operations	Project Integration and Test: During the latter period of project integration and test, the system is tested by performing operational simulations during functional and environmental testing. The simulations typically exercise the end-to-end command and data system to provide a complete verification of system functionality and performance against simulated project operational scenarios.
	Launch Integration: The launch integration phase may repeat integration and test operational and functional verification in the launch integrated configuration.
Launch operations	Launch: Launch operation occurs during the launch countdown, launch ascent, and orbit injection. Critical event telemetry is an important driver during this phase.
	Deployment: Following orbit injection, spacecraft deployment operations reconfigure the space- craft to its orbital configuration. Typically, critical events covering solar array, antenna, and other deployments and orbit trim maneuvers occur during this phase.
	In-Orbit Checkout: In-orbit checkout is used to perform a verification that all systems are healthy. This is followed by on-orbit alignment, calibration, and parameterization of the flight systems to prepare for science operations.
Science operations	The majority of the operational lifetime is used to perform science operations.
Safe-hold operations	As a result of on-board fault detection or by ground command, the spacecraft may transition to a safe-hold mode. This mode is designed to maintain the spacecraft in a power positive, thermally stable state until the fault is resolved and science operations can resume.
Anomaly resolution and maintenance operations	Anomaly resolution and maintenance operations occur throughout the mission. They may require resources beyond established operational resources.
 Disposal operations	Disposal operations occur at the end of project life. These operations are used to either provide a controlled reentry of the spacecraft or a repositioning of the spacecraft to a disposal orbit. In the latter case, the dissipation of stored fuel and electrical energy is required.

JWST Deployment Video

JWST Deployment Video

https://www.youtube.com/watch?v=N8h_6WgSMjs

Concept Question 10

- How long is the commissioning phase of the James Webb Space Telescope (JWST) before science operations can begin?
- 3 days
- 1 week
- 3 weeks
- 1 month
- 3 months
- 6 months
- Not sure

Answer Concept Question 10 (see supplemental files)

JWST Science Planning Timeline (as of 2014 Feb)



JWST Timeline to Operations

Commissioning Program [6 mo: 2018 Oct-2019 Apr]

- full schedule of deployment & check-out activities
- limited set of science calibration obs possible
- science obs highly unlikely

Guest Observer Program [2019 Apr -]

- use GO programs from HST, Spitzer, etc. as models
- will accommodate programs with range of sizes
- support archival research
- details TBD, consultations with JSTAC

Guaranteed Time Observation Program [2019 Apr -]

- 3,960 hr total allocation in first 30 mo. after commissioning
- ~10% of time available in nominal 5 yr lifetime

Source: Janice C. Lee STScI Science Mission Office March 13, 2014

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Some research into operations

Siddiqi A., de Weck O., "Spare Parts Requirements for Space Missions with Reconfigurability and Commonality", *Journal of Spacecraft and Rockets*, <u>44</u> (1), 147-155, January-February 2007

Impact of Reconfigurability on Logistics

- Reconfigurability across different elements in a mission was explored
- Effect of reconfigurable spares on system availability was quantified through allowance of temporary scavenging/cannibalization

Element Operational Profiles





- The number of available spares become a function of time
- System availability as function of spares level will be used for quantifying impact

Spare Parts Requirements Model - I

Failures modeled as Poisson process

$$p(n) = \frac{e^{-t} / n}{n!}$$
$$\lambda = \int_{t_o}^{t_f} ldt = ql\Delta t$$
$$l_e(t_i) = q_e l \overset{i}{\overset{i}{\underset{k=1}{\otimes}}} [t_k - t_{k-1}] G_e(t_k)$$

Spares from elements are function of time (operation profile)

$$s_{E}(t_{i}) = \bigotimes_{e=1}^{E} q_{e}[\varnothing G_{e}(t_{i})]$$
$$s(t_{i}) = s_{I} + s_{E}(t_{i}) - n_{F}$$

q: quantity per application (QPA) λ : mean failures n_f : # of failures p(n): probability of n failures I : failure rate Γ : binary variable for operation s_E : spares from elements s_I : spares from repository s: total spares



Reconfigurable Parts



Spare Parts Requirements Model - II

Number of failures is limited by total parts due to no re-supply and repair:

$$0 \notin n_F \notin N$$
$$N = s_I + \bigotimes_{e=1}^{E} q_e$$

For independent failures, the probability of no outstanding part order is:

$$A(t_i) = \overset{\mathfrak{A}}{\underset{e}{\Diamond}} - \frac{\overline{B}(t_i) \overset{o}{\overset{o}{\partial}}}{Q} \overset{e}{\overset{e}{\otimes}}$$

Expected backorder level is function of available spares (and therefore of time):

$$A_{sys} = \min[A(t_i)] \quad t_i \hat{l} \quad T$$

$$\overline{B}_{c}(s,t_{i}) = \overset{N}{\underset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_{F}=s+1}{\overset{n_$$

 $\mathbf{\lambda}I$

N: total number of parts $B_c(s,t)$: conditional backorder at spares level s P(s): probability of s spares being available $A(t_i)$: Availability at time t_i

Quantifying the Impact of Reconfigurability

- Define co-located mission elements
- Define operational time profile, QPA etc.
- An Electronic Control Unit (ECU) with 100,000 hrs MTTF was used as an example





 Reconfigurable parts allow for 33-50% reduction in number of required spares for 90% Availability level

Benefits and Limitations

Increase in availability may be traded for reduced reliability (to affect component cost)



There is an eventual tradeoff between reconfigurable and dedicated parts if failure rates become high enough

Robustness of degraded aircraft (USAF)

- Aerospace systems spend significant time operating in degraded or off-nominal states
 - Yet current early-stage design focuses on improving performance in the nominal or most-likely state.
 - Future ultra long endurance vehicles require more attention to robustness in off-nominal states

Robustness – ability to perform under a variety of circumstances; ability to deliver desired functions in spite of changes in the environment, uses, or internal variations that are either built-in or emergent





DARPA – Vulture



Vulture – stay aloft 5 years No landing + repair allowed

NASA Antarctica UAV mission



5 years, 50kft, map ice sheets Replace or complement IceSat



Space Colonization

King Air Twin Engine Case Study





Expected Performance

minimize
$$-E_G(\mathbf{x}, \mathbf{c}) = -\sum_{k=1}^{K} p_k G(\mathbf{x}, \mathbf{c})_k \text{ or } -E_A(\mathbf{x}, \mathbf{c}) = -\sum_{m=1}^{M} A(W_M) \frac{T_M}{T}$$

s.t. $\mathbf{h}(\mathbf{x}, \mathbf{c}) = 0$
 $\mathbf{g}(\mathbf{x}, \mathbf{c}) = \mathbf{G}_{N, req} / \mathbf{G}_N(\mathbf{x}, \mathbf{c}) - 1 \le 0$
 $x_{i,LB} \le x_i \le x_{i,UB}$

Agte J., Borer N., de Weck O., "Multistate Design Approach to the Analysis of Performance Robustness for a Twin-Engine Aircraft", *Journal of Aircraft*, <u>49</u>(3), 781-793, May-June 2012

State	Left Engine	Rudder	Ailerons	Turn control
Ν				ailerons
1	failed			ailerons
2		failed		ailerons
3			failed	rudder
4	failed		failed	rudder
5	failed	failed		ailerons
6		failed	failed	diff. thrust
7	failed	failed	failed	none

Aircraft Design Space

Design Variable:	Low Value	Baseline	High Value
Wing Area	$272.7 ft^2$	$303 ft^2$	$333.3 ft^2$
Wing Span	$49.05 \ ft$	54 ft	59.95 ft
Horizontal Tail Area	$65.7 ft^2$	$73 ft^2$	$80.3 ft^2$
Horizontal Tail Span	$16.51 \ ft$	18.3 ft	20.17 ft
Vertical Tail Area	$105.12 \ ft^2$	$116.8 ft^2$	$128.48 ft^2$
Vertical Tail Height	7.5 ft	8.33 ft	9.16 ft
Spanwise Engine Location	7.72 ft	8.58 ft	9.44 ft
Aileron Chord [*]	15.3%	23%	30.7%
Elevator Chord [*]	35.1%	41%	46.9%
Rudder Chord [*]	38.4%	44%	49.6%
Wing Sweep	0 deg	4 deg	15 deg

*Given in percent of wing, horizontal tail, or vertical tail chord.

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Robustness requires off-nominal design optimization

Key result: aircraft geometry influences long-duration performance robustness more than component failure rates λ_i . Off-nominal control needed.



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- Post-Flight Review (PFR)

Post Flight Assessment Review (PFR)

- Also known as Post Launch Review (PLR)
 - Review telemetry from flight
 - Compare against predictions (e.g. from simulation)
 - Find / repair any failures
 - Secure data for later use
 - Initiate detailed commissioning / handover to operators
- A PFR-like review is part of the 2016 Cansat Competition

Table 6.7-18 PFAR Entrance and Success Criteria

Post-Flight Assessment Review				
Entrance Criteria	Success Criteria			
 All anomalies that occurred	 Formal final			
during the mission, as well	report docu-			
as during preflight testing,	menting flight			
countdown, and ascent,	performance and			
identified.	recommenda-			
2. Report on overall post-recov-	tions for future			
ery condition.	missions.			
 Report any evidence of ascent	2. All anomalies			
debris.	have been			
 All photo and video documentation available. 	documented and disposed.			
 Retention plans for scrapped	 The impact of			
hardware completed.	anomalies on			
 Post-flight assessment team	future flight			
operating plan completed.	operations has			
 Disassembly activities	been assessed.			
planned and scheduled.	4. Plans for retain-			
 Processes and controls to	ing assessment			
coordinate in-flight anomaly	documentation			
troubleshooting and post-	and imaging			
flight data preservation	have been made.			
developed.	5. Reports and			
 Problem reports, corrective	other docu-			
action requests, post-flight	mentation have			
anomaly records, and final	been added to			
post-flight documentation	a database for			
completed.	performance			
 All post-flight hardware and flight data evaluation reports completed. 	comparison and trending.			

Summary: Ops Checklist

- System checkout in lab/hangar/field; everything working OK?
- Bring sufficient consumables (batteries, fuel, lubricants etc...), including reserves
- Spare parts and tools to repair
- Other support equipment (remote control, telemetry, cameras ...)
- Training operators and support personnel
- Checklist for normal operations and emergency/contingencies
- Transportation logistics (forward and reverse)
- Plan in enough time for commissioning \rightarrow before operations

Reminders for PDR (next week)

- Check Schedule be on time
- Upload slide deck beforehand
- 30 min PDR presentation
- Followed by up to 30 min Q&A



Questions?

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