

Variational Method

(See CTDL 1148-1155, [Variational Method]
252-263, 295-307[Density Matrices])

Last time:

Quasi-Degeneracy → Diagonalize a part of infinite \mathbf{H}

* sub-matrix : $\mathbf{H}^{(0)} + \mathbf{H}^{(1)}$

* corrections for effects of out-of-block elements: $\mathbf{H}^{(2)}$
(the Van Vleck transformation)

*diagonalize $\mathbf{H}^{\text{eff}} = \mathbf{H}^{(0)} + \mathbf{H}^{(1)} + \mathbf{H}^{(2)}$

coupled H-O's 2 : 1 ($\omega_1 \approx 2\omega_2$) Fermi resonance example: polyads

1. Perturbation Theory vs. Variational Method
2. Variational Theorem
3. Stupid nonlinear variation
4. Linear Variation → new kind of secular Equation
5. Linear combined with nonlinear variation
6. Strategies for criteria of goodness — various kinds of variational calculations

1. Perturbation Theory vs. Variational Method

Perturbation Theory in effect uses ∞ basis set

goals: parametrically parsimonious fit model, \mathbf{H}^{eff}

fit parameters (molecular constants) \leftrightarrow parameters that define $V(x)$

order - sorting $\frac{H_{nk}^{(1)}}{E_n^{(0)} - E_k^{(0)}} < 1$ — errors less than this “mixing angle” times the previous order non-zero correction term

(n is in-block, k is out-of block) because diagonalization is ∞ order (within block).

Variational Method



best possible estimate for lowest few E_n , ψ_n (and properties derivable from these) using finite basis set and exact form of \mathbf{H} .

Vast majority of computer time in Chemistry is spent in variational calculations
Goal is numbers. Insight is secondary.

“*Ab Initio*” vs. “semi-empirical” or “fitting”

[intentionally bad basis set: Hückel, tight binding –
qualitative behavior obtained by a fit to a few microscopic–like
control parameters]

2. Variational Theorem

not necessarily
normalized

any observable

If ϕ is approximation to eigenfunction of \hat{A}
belonging to lowest eigenvalue a_0 , then

$$\alpha \equiv \frac{\langle \phi | \hat{A} | \phi \rangle}{\langle \phi | \phi \rangle} \geq a_0$$

the variational Theorem

PROOF: eigenbasis (which we do not know – but know it must exist)

$$\hat{A} |n\rangle = a_n |n\rangle$$

expand ϕ in eigenbasis of \hat{A} , exploiting completeness

$$|\phi\rangle = \sum_n |n\rangle \langle n | \phi \rangle$$

$$\langle \phi | \hat{A} | \phi \rangle = \sum_{n, n'} \langle \phi | n \rangle \underbrace{\langle n | \hat{A} | n' \rangle}_{\substack{a_n \delta_{nn'} \\ \text{eigenbasis}}} \langle n' | \phi \rangle = \sum_n |\langle \phi | n \rangle|^2 a_n$$

$$\langle \phi | \phi \rangle = \sum_n \langle \phi | n \rangle \langle n | \phi \rangle = \sum_n |\langle \phi | n \rangle|^2$$

$$\alpha \equiv \frac{\langle \phi | \hat{A} | \phi \rangle}{\langle \phi | \phi \rangle} = \frac{\sum_n a_n |\langle n | \phi \rangle|^2}{\sum_{n'} |\langle n' | \phi \rangle|^2}$$

all terms in both sums are ≥ 0

subtract a_0 from both sides

$$\alpha - a_0 = \frac{\sum_n (a_n - a_0) |\langle n | \phi \rangle|^2}{\sum_{n'} |\langle n' | \phi \rangle|^2} \geq 0$$

again, all terms in
both sums are ≥ 0

5.73 Lecture #18

18 - 3

because, by definition of a_0 , $a_n \geq a_0$ for all n and all terms in sum are $\therefore \geq 0$.

$$\therefore \alpha \geq a_0. \quad \text{QED} \quad \left(\begin{array}{l} \text{but useless because we} \\ \text{can't know } a_n \text{ or } \langle n | \phi \rangle \end{array} \right)$$

It is possible to perform a variational calculation for any \mathbf{A} , not limited to \mathbf{H} .

3. Stupid Nonlinear Variation

Use the wrong functional form or the wrong variational criterion to get poor results — illustrates that the variational function must have sufficient flexibility and the variational criterion must be as it is specified in the variational theorem, as opposed to a clever shortcut.

The H atom Schr. Eq. ($\ell = 0$)

$$\mathbf{H} = \underbrace{-\frac{1}{2} \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r}}_{\text{T}} \quad \underbrace{-\frac{1}{r}}_{\text{V}}$$

and we know $\left\{ \begin{array}{l} \psi_{1s}(r) = \langle r | 1s \rangle = \pi^{-1/2} e^{-r} \\ E_{1s} = -1/2 \text{ au} \end{array} \right. \quad [1 \text{ au} = 219475 \text{ cm}^{-1}]$

but try $\langle r | \phi \rangle = [\xi^3 / 2\pi]^{1/2} (\xi r) e^{-\xi r}$ normalized
for all ξ

ξ is a scale factor that controls overall size of $\phi(r)$

[actually this is the form of $\psi_{2p}(r)$] which is necessarily orthogonal to ψ_{1s} ! STUPID!

$$\left(\phi(0) = 0 \quad \text{but} \quad \psi_{1s}(0) = \pi^{-1/2} \right)$$

$$\varepsilon = \frac{\langle \phi | \mathbf{H} | \phi \rangle}{\langle \phi | \phi \rangle} = \frac{4}{3} \left(\frac{\xi^2 - 3\xi}{8} \right) \quad \text{skipped a lot of algebra}$$

minimize ε : $\frac{d\varepsilon}{d\xi} = 0 \quad \xi_{\min} = 3/2 \rightarrow \varepsilon_{\min} = -3/8 \text{ au}$

FAILURE! $\left[\text{c.f. the true values: } E_{1s} = -1/2 \text{ au}, E_{2s} = -\frac{1}{8} \text{ au} \right]$

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18 - 4

Try something clever (but lazy):

What is the value of ξ that maximizes $\langle \phi | 1s \rangle$?

for the best variational $\xi = 3/2$, $C_{1s} \equiv \langle \phi(\xi = 3/2) | 1s \rangle = 0.9775$

if we maximize C_{1s} wrt. ξ : $\xi = 5/3 \rightarrow C_{1s} = 0.9826$ better?

but $\varepsilon = -0.370$ results, a poorer bound than $\xi = 3/2 \rightarrow \varepsilon = -0.375$

* need flexibility in ϕ

* can improve on $\frac{d\varepsilon}{d\xi}$ by employing an alternative variational strategy

This was stupid anyway because we would never use the variational method when we already know the answer!

4. Linear Variation \rightarrow Secular Equation

$$\phi = \sum_{n=1}^N c_n \chi_n$$

$$\langle \chi_n | \mathbf{H} | \chi_{n'} \rangle = H_{nn'}$$

$$\langle \chi_n | \chi_{n'} \rangle = S_{nn'}$$

overlap integrals
(non-orthogonal basis sets are often convenient)



$$\varepsilon = \frac{\langle \phi | \mathbf{H} | \phi \rangle}{\langle \phi | \phi \rangle} = \frac{\sum_{n,n'} c_n c_{n'} H_{nn'}}{\sum_{m,m'} c_m c_{m'} S_{mm'}} \quad \text{rearrange this equation}$$

$$\varepsilon \sum_{m,m'} c_m c_{m'} S_{mm'} = \sum_{n,n'} c_n c_{n'} H_{nn'}$$

to find minimum value of ε ,

take $\frac{\partial}{\partial c_j}$ for each j and require that

$$\frac{\partial \varepsilon}{\partial c_j} = 0 \text{ for each } j \quad \boxed{\text{linear variation!}}$$

because we are seeking to minimize ε with respect to each c_j .

Find the global minimum of the $\varepsilon(c_1, c_2, \dots, c_N)$ hypersurface.

the only terms that survive $\frac{\partial}{\partial c_j}$ are those that include c_j .

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18 - 5

$$\epsilon \sum_m c_m (S_{mj} + S_{jm}) = \sum_n c_n (H_{jn} + H_{nj})$$

if $\{\chi_n\}$ are real $S_{ij} = S_{ji}, H_{ij} = H_{ji}$

$$0 = \sum_{n=1}^N c_n (H_{jn} - \epsilon S_{jn})$$

These are all of the surviving terms (i.e. those that include j). Each j term appears twice in both sums, once as a bra and once as a ket.

one such equation for each j (same set of unknown $\{c_n\}$)

N linear homogeneous equations in N unknown c_n 's

Non trivial $\{c_n\}$ only if $|\mathbf{H} - \epsilon \mathbf{S}| = 0$

(Not same form as $|\mathbf{H} - \mathbb{1}E| = 0$)

The result is N special values of ϵ that satisfy this equation.

CTDL show: all N ϵ_n values are upper bounds to the lowest N E_n 's

and all $\{\phi_n\}$'s are orthogonal! (provided that they belong to different

How to solve $|\mathbf{H} - \epsilon \mathbf{S}| = 0$

values of E_n)

1. Diagonalize \mathbf{S}

$$\mathbf{U}^\dagger \mathbf{S} \mathbf{U} = \tilde{\mathbf{S}} \quad \tilde{S}_{ij} = s_i \delta_{ij}$$

(orthogonalize $\{\chi\}$ basis)

2. Normalize $\tilde{\mathbf{S}}$

$$\underbrace{(\tilde{\mathbf{S}})^{-1/2} \tilde{\mathbf{S}} (\tilde{\mathbf{S}})^{-1/2}}_{\substack{3 \text{ diagonal} \\ \text{matrices}}} = \mathbf{1} \equiv \tilde{\tilde{\mathbf{S}}} = \mathbf{T}^\dagger \mathbf{S} \mathbf{T} \quad \left(\mathcal{S}^{-1/2} \right)^\leq = \mathcal{S}^{-1/2} = \begin{pmatrix} s_1^{-1/2} & 0 & 0 \\ 0 & s_2^{-1/2} & 0 \\ 0 & 0 & \ddots \end{pmatrix}$$

where $\mathbf{T} = \mathbf{U} \mathbf{S}^{-1/2}$

unitary

This is not an orthogonal transformation, but it does not destroy orthogonality because each function is only being multiplied by a constant.

3. Transform \mathbf{H} to orthonormalized basis set

$$\tilde{\mathbf{H}} = \underbrace{\mathbf{S}^{-1/2}}_{\mathbf{T}^\dagger} (\mathbf{U}^\dagger \mathbf{H} \mathbf{U}) \underbrace{\mathbf{S}^{-1/2}}_{\mathbf{T}}$$

\mathbf{U} diagonalizes \mathbf{S}
not \mathbf{H}

new secular equation

$$|\tilde{\mathbf{H}} - \epsilon \tilde{\mathbf{S}}| = 0 \quad \text{but} \quad \tilde{\mathbf{S}} = \mathbf{1}$$

$$|\tilde{\mathbf{H}} - \epsilon \mathbf{1}| = 0 \quad \text{usual} \quad \tilde{\mathbf{H}} \quad \text{diagonalized by usual procedure!}$$

5. Combine Linear and Nonlinear Variation

typically done in *ab initio* electronic structure calculations

Basis set: $\chi_n(\xi_n r)$ linear variation where ϵ_n is a radial scale factor

$$\Psi = \sum_n c_n \chi_n(\xi_n r)$$

nonlinear variation

$$S_{nn'}(\xi_n, \xi_{n'}), H_{nn'}(\xi_n, \xi_{n'})$$

0. pick arbitrary set of $\{\xi_i\}$
1. calculate all $H_{ij}(\xi_i, \xi_j)$ & $S_{ij}(\xi_i, \xi_j)$
2. Solve $|\mathbf{H} - \epsilon \mathbf{S}| = 0$
 - a. $\mathbf{S} \rightarrow \tilde{\mathbf{S}}$ diagonalize \mathbf{S} (orthogonalize)
 - b. $(\tilde{\mathbf{S}})^{-1/2}$ (normalize)
 - c. $\mathbf{H} \rightarrow \tilde{\mathbf{H}}$
 - d. diagonalize $\tilde{\mathbf{H}}$

nonlinear variation begins – find global minimum of ϵ_{lowest} with respect to each ξ_i

3. change ξ_1 from $\xi_1^{(0)} \rightarrow \xi_1^{(1)} = \xi_1^{(0)} + \delta$
4. recalculate all integrals in \mathbf{H} and \mathbf{S} involving χ_1
5. Solve $|\mathbf{H} - \epsilon\mathbf{S}| = 0$ to obtain a new set of $\{\epsilon_i\}$.
Pick lowest ϵ_i .
6. calculate
$$\frac{\partial \epsilon_{\text{lowest}}}{\partial \xi_1} = \frac{\epsilon_{\text{lowest}}^{\text{old}} - \epsilon_{\text{lowest}}^{\text{new}}}{\xi_1^{(0)} - \xi_1^{(1)}}$$
7. repeat #3 – 6 for each ξ_i (always looking only at lowest ϵ_i)
This defines a gradient on a multidimensional $\epsilon(\xi_1, \dots, \xi_N)$ surface. We seek the minimum of this hypersurface. Take a step in direction of steepest descent by an amount determined by $|\partial \epsilon / \partial \xi_{\text{steepest}}|$ (small slope, small step; large slope, large step).

This completes 1st iteration. All values of $\{\xi_i\}$ are improved.
8. Return to #3, iterate #3-7 until convergence is obtained.

Nonlinear variations are much slower than linear variations.

Typically use ENORMOUS LINEAR $\{\chi\}$ basis set.

Contract this basis set by optimizing nonlinear parameters (exponential scale factors) in a SMALL BASIS SET to match the lowest $\{\phi\}$'s that had initially been expressed in large basis set.

6. Alternative Strategies

- * rigorous variational minimization of E_{lowest} : “*ab initio*”
- * constrain variational function to be orthogonal to specific subset of functions

e.g. orthogonal to ground state – to get variational convergence.
 Applies only to higher members of specific symmetry class
 or orthogonal to core: frozen-core approximation.
 “Pseudopotentials” (use some observed energy levels to determine $Z^{\text{eff}}(r)$ of frozen core)

- * least squares fitting

minimize differences between a set of measured energy levels (or other properties) and a set of computed variational eigen-energies (or other properties computed from variational wavefunctions).

$$\begin{array}{c} \{\text{observed } E_n\} \leftrightarrow \{\text{parameters in } \mathbf{H}^{\text{eff}}\} \\ \text{molecular constants} \\ \Downarrow \\ \text{experimental } \psi \text{ 's in finite} \\ \text{variational basis set} \end{array}$$

- * semi-empirical model

replace exact $\hat{\mathbf{H}}$ by a grossly simplified form and restrict basis set to a simple form too.

Then adjust parameters in \mathbf{H} to match some observed pattern of energy splittings. Use parameters to predict unobserved properties or use values of fit parameters to build insight.