1.00 Lecture 32

Integration

Reading for next time: Numerical Recipes 347-368







Elementary Integration Methods public class Quartic implements MathFunction { public double f(double x) { // f in MathFunction return x*x*x*x +2; } } public class Integration { public static double rect(MathFunction func, double a, double b, int n) { double h = (b-a)/n; double answer=0.0; for (int i=0; i < n; i++)</pre> answer += func.f(a+i*h); // Left edge return h*answer; ł public static double trap(MathFunction func, double a, double b, int n) { double h = (b-a)/n; double answer= func.f(a)/2.0; for (int i=1; i <= n; i++)</pre> answer += func.f(a+i*h); // Common edge answer -= func.f(b)/2.0; return h*answer; }

```
Elementary Integration Methods, p.2
public static double simp(MathFunction func,
                   double a, double b, int n) {
       // Each panel has area (h/6)*(f(x) + 4f(x+h/2) + f(x+h))
       double h = (b-a)/n:
       double answer= func.f(a);
       for (int i=1; i <= n; i++)
           answer += 4.0*func.f(a+i*h-h/2.0)+ 2.0*func.f(a+i*h);
       answer -= func.f(b);
       return h*answer/6.0;
                               }
   public static void main(String[] args) {
      double r= Integration.rect(new Quartic(), 0.0, 8.0, 200);
      System.out.println("Rectangle: " + r);
      double t= Integration.trap(new Quartic(), 0.0, 8.0, 200);
      System.out.println("Trapezoid: " + t);
      double s= Integration.simp(new Quartic(), 0.0, 8.0, 100);
      System.out.println("Simpson: " + s);
  }
// Problems: no accuracy estimate, inefficient, only closed int
```













Using Trapezoidal Rule

- Keep cutting intervals in half until desired accuracy met
 - Estimate accuracy by change from previous estimate
 - Each halving requires only half the work because past work is retained
- By using a quadratic interpolation (Simpson's rule) to function values instead of linear (trapezoidal rule), we get better error behavior
 - By good fortune, errors cancel well with quadratic approximation used in Simpson's rule
 - Computation same as trapezoid, but uses different weighting for function values in sum





Extended Simpson Method public class Simpson { // NumRec p. 139 public static double qsimp(MathFunction func, double a, double b) { double ost= -1.0E30; double os= -1E30; for (int j=0; j < JMAX; j++) { double st= Trapezoid.trapzd(func, a, b, j+1); s= (4.0*st - ost)/3.0; // See NumRec eq. 4.2.4 // Avoid spurious early convergence if (j > 4) if (Math.abs(s-os) < EPSILON*Math.abs(os) || (s==0.0 && os==0.0)) { System.out.println("Simpson iter: " + j); return s; } OS= S; ost= st; System.out.println("Too many steps in qsimp"); return ERR_VAL; } private static double s; // Value of integral public static final double EPSILON= 1.0E-15; public static final int JMAX= 50; public static final double ERR_VAL= -1E10; }





Romberg Integration

• Generalization of Simpson (NumRec p. 140)

- Based on numerical analysis to remove more terms in error series associated with the numerical integral
 - Uses trapezoid as building block as does Simpson
- Romberg is adequate for smooth (analytic) integrands, over intervals with no singularities, where endpoints are not singular
- Romberg is much faster than Simpson or the elementary routines. For a sample integral:
 - Romberg: 32 iterations
 - Simpson: 256 iterations
 - Trapezoid: 8192 iterations
- All are instances of Newton-Cotes methods



















1.00 / 1.001 / 1.002 Introduction to Computers and Engineering Problem Solving Spring 2012

For information about citing these materials or our Terms of Use, visit: http://ocw.mit.edu/terms.