

**Structures - Class Exercise 1a.**  
**1.101 Sophomore Design - Fall 2006**

Given the differential equation:  $\frac{d^2}{dx^2}w(x) = \frac{Q_o}{EI} \cdot (L - x)$  on  $0 \leq x \leq L$  where capitalized letters

are constants. The boundary conditions are  $\left. \frac{dw}{dx} \right|_{x=0} = 0$  and  $w|_{x=0} = 0$

Find  $w(x) = ?$   $\left. \frac{dw}{dx} \right|_{x=L} = ?$  and  $w|_{x=L} = ?$

From direct integration of the differential equation  $w(x) = \frac{Q_o}{EI} \cdot \left( \frac{x^2}{2}L - \frac{x^3}{6} \right) + c_1 \cdot x + c_2$

From the boundary conditions, the two constants of integration must be zero, so

$$w(x) = \frac{Q_o}{EI} \cdot \left( \frac{x^2}{2}L - \frac{x^3}{6} \right) \quad \text{and} \quad \frac{d}{dx}w(x) = \frac{Q_o}{EI} \cdot \left( xL - \frac{x^2}{2} \right)$$

Then, at  $x=L$ , the deflection,  $w(L) = \Delta$ , and the slope,  $\left. \frac{dw}{dx} \right|_{x=L} = \phi(L)$  are

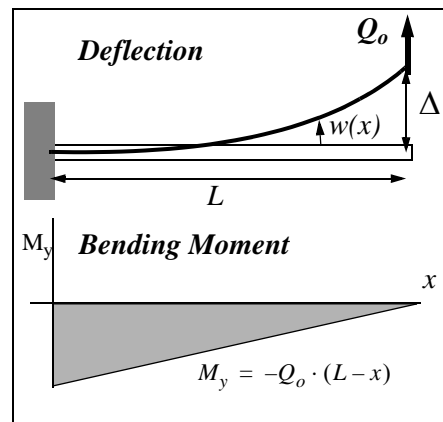
$$\Delta = w(L) = \frac{Q_o \cdot L^3}{3EI} \quad \text{and} \quad \phi(L) = \left. \frac{d}{dx}(w) \right|_{x=L} = \frac{Q_o \cdot L^2}{2EI}$$

What does all this have to do with the picture shown?

$Q_o$  is the end load.  $w(x)$  is the deflection. The differential equation we start with is the “moment-curvature” relation.

For small deflections and rotations,  $\frac{d^2}{dx^2}w(x)$  is the

curvature (positive concave upwards). The right hand side is the bending moment which, by convention of 1.050, is taken as positive when the curvature is concave downwards.  $M_y = -Q_o \cdot (L - x)$



**Structures - Class Exercise 1b.**  
**1.101 Sophomore Design - Fall 2006**

Given the differential equation:  $\frac{d^2}{dx^2}w(x) = \frac{-M_o}{EI}$  on  $0 \leq x \leq L$  where all capitalized

letters are constants. The boundary conditions are  $\left. \frac{dw}{dx} \right|_{x=0} = 0$  and  $w|_{x=0} = 0$

Find  $w(x) = ?$   $\left. \frac{dw}{dx} \right|_{x=L} = ?$  and  $w|_{x=L} = ?$

As in the previous exercise, we find, after applying the boundary conditions

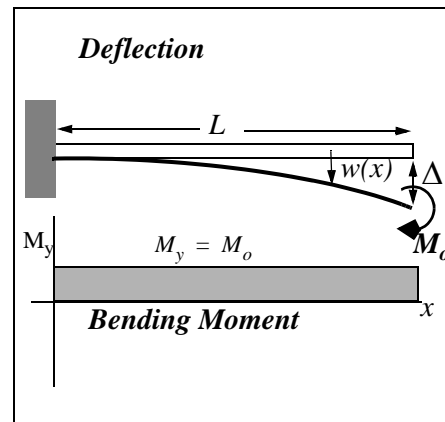
$$w(x) = \frac{-M_o x^2}{2EI} \quad \text{and} \quad \left. \frac{dw}{dx} \right|_{x=L} = \frac{-M_o x}{EI}$$

Then, at  $x=L$ , the deflection,  $w(L) = \Delta$ , and the slope,  $\left. \frac{dw}{dx} \right|_{x=L} = \phi(L)$  are

$$\Delta = w(L) = \frac{-M_o L^2}{2EI} \quad \text{and} \quad \phi(L) = \left. \frac{d}{dx}(w) \right|_{x=L} = \frac{-M_o L}{EI}$$

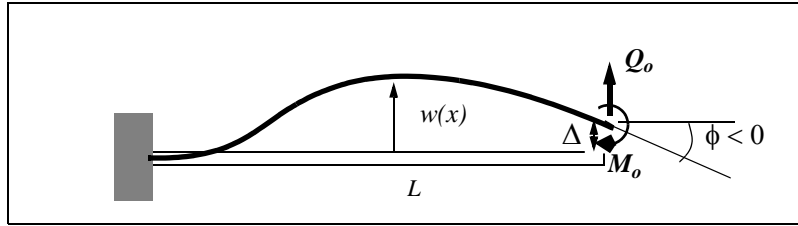
What does all this have to do with the picture shown?

Here,  $M_o$  is the *applied moment* at the end of the beam. Within the beam,  $0 < x < L$ , the bending moment is constant and equal to the applied moment. It is positive according to our convention.



We now superimpose these two loading cases to solve a more general problem and one that is relevant to your design task.

For the cantilever under end load and end moment, the deflected shape might look as shown .



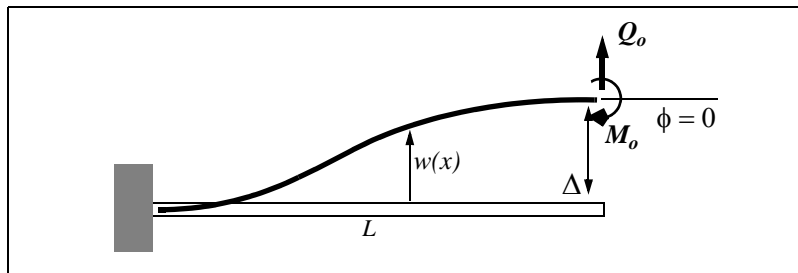
For this combined loading, we have:

$w(x) = \frac{Q_o}{EI} \cdot \left( \frac{x^2}{2}L - \frac{x^3}{6} \right) + \frac{-M_o x^2}{2EI}$	$\frac{d}{dx}w(x) = \frac{Q_o}{EI} \cdot \left( xL - \frac{x^2}{2} \right) + \frac{-M_o x}{EI}$
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At the end of the beam, we have:

$\Delta = \frac{Q_o \cdot L^3}{3EI} - \frac{M_o L^2}{2EI}$	and	$\phi(L) = \frac{Q_o \cdot L^2}{2EI} - \frac{M_o L}{EI}$
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We want the solution for the special case when the slope at  $x = L$  is zero.



Setting  $\phi(L) = 0$  gives the applied end moment in terms of the end force  $M_o|_{\phi(L)=0} = \frac{Q_o \cdot L}{2}$

So, in this case, the tip deflection is  $\Delta = \frac{Q_o \cdot L^3}{12EI}$  or, expressing  $Q_o$  in terms of the displacement,

$Q_o = K \cdot \Delta$	where the stiffness, K, is	$K = \frac{12 \cdot EI}{L^3}$
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## Engineering Beam Theory

Engineering beam theory shows that the most significant stress is the normal stress component on an “x face”;  $\sigma_x$  in the example at the right. It is related to the applied loads by

$$\sigma_x = \frac{M_y \cdot z}{I}$$

where  $z$  is the distance from the “neutral axis” which, for a doubly symmetric beam, is at the center of the cross-section and  $I$  is the moment of inertia of the cross section.

$$I = \int_A z^2 dA$$

For a rectangular cross-section of width  $b$  and height  $h$ , this is  $I = bh^3/12$

The applied loads come in through the bending moment  $M_y$ . The convention for positive shear and bending moment is shown in the figure.

The extensional strain, from the stress/strain relations is just  $\epsilon_x = \sigma_x/E$  where  $E$  is the Elastic Modulus. In terms of the geometry of deformation, the extensional strain is given by  $\epsilon_x = z/R$  where  $R$  is the radius of curvature of the neutral axis.  $(1/R)$  is the curvature. The “bending stiffness” is defined as the product  $E I$  as it appears in the “moment-curvature” relationship  $M_y = (EI) \cdot \left(\frac{1}{R}\right)$  where the curvature, for small deflections, is related to the vertical displacement of the neutral axis by,  $(1/R) = -d^2w/dx^2$

or . 
$$\boxed{-M_y/(EI) = \frac{d^2}{dx^2}w(x)}$$

An integration of the differential equation obtained from the moment curvature relation gives, for the case where the beam is loaded as shown, the mid-span deflection

$$w|_{midspan} = -\left(\frac{Pa}{24EI}\right) \cdot (3L^2 - 4a^2)$$

