Notes on Non-linear Taxation

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1 Income Taxation

1.1 Setup

- two goods (alternatively, other goods untaxed, perhaps because of Atkinson-Stiglitz case)
- Preference

$$U^i(c,Y) = U(c,Y,\theta^i)$$

• Technology

$$G + \int (c(\theta) - Y(\theta))dF(\theta) \le e$$

- *F* can be continuous or not (e.g. with finite types $G + \sum_{i} (c(\theta^{i}) Y(\theta))\pi^{i} \leq e$)
- Income taxation: budget constraint is

$$B = \{(c, Y) | c \le Y - T(Y)\}$$

for some T(Y).

- call $R(Y) \equiv Y T(Y)$ the retention function
- Normative Criterion?
 - 1. Welfare function (Mirrlees, 1971)
 - 2. Pareto efficiency

1.2 Feasibility and Incentive compatibility

• agent behavior

$$\max_{c,Y} U^i(c,Y) \qquad \text{s.t.} c \le Y - T(Y) = R(Y)$$

- <u>Definition</u>. An allocation and a tax function c, Y, T is feasible if: (i) RC holds; (ii) agents maximize $\{c(\theta), y(\theta)\}$ given T(Y) [given R(Y)]
- An allocation $c(\theta), Y(\theta)$ is feasible if there exists a tax function that makes c, Y, T feasible.
- Note that resource constraint is the same as...

$$G - e \le \int T(Y(\theta)) dF(\theta)$$

government budget constraint.

• Observation: if *c*, *Y* is feasible then

$$u(c(\theta), Y(\theta), \theta) \ge u(c(\theta'), Y(\theta'), \theta)$$
 for all $\theta, \theta \in \Theta$

Incentive Compatibility Constraints (IC)

• Converse also true:

$$R(\tilde{Y}) \equiv \sup\{\tilde{c}|u(c(\theta), Y(\theta), \theta) \ge u(\tilde{c}, \tilde{Y}, \theta) \text{ for all } \theta\}$$

IC holds \implies if agents faced with *R* then optimum is attainable (optimal by definition of *R*)

- note: R(Y) continuous by theorem of the max.
- Taxation principle and revelation principle
- Marginal taxes: if $T'(\tilde{Y})$ exists and $\tilde{Y} = Y(\theta)$ for some θ then

$$T'(\tilde{Y}) = T'(Y(\theta)) = 1 - MRS(c(\theta), Y(\theta), \theta)$$

where

$$MRS(c, Y, \theta) \equiv -\frac{U_Y(c, Y, \theta)}{U_c(c, Y, \theta)}$$

• Single crossing

 $MRS(c, Y, \theta)$ is decreasing in θ

- Single crossing $\implies c(\theta)$ and $y(\theta)$ non-decreasing
- Finite types: Single crossing \implies local IC are sufficient

$$\begin{array}{rcl} u(c(\theta^{i}), y(\theta^{i}), \theta^{i}) & \geq & u(c(\theta^{i-1}), y(\theta^{i-1}), \theta^{i}) \\ u(c(\theta^{i-1}), y(\theta^{i-1}), \theta^{i-1}) & \geq & u(c(\theta^{i}), y(\theta^{i}), \theta^{i-1}) \end{array}$$

[homework: show others are implied]

• note: local IC's imply monotonicity

1.3 Two types case

- Assume $\Theta = \{\theta_L, \theta_H\}$ with $\theta_L < \theta_H$
- result 1: pooling is inefficient ...only one IC binds
- result 2: for binding agent we have MRS = 1
 ... no taxation at the top.
- result 3: Pareto frontier has 3 regions
 - 1. First best
 - 2. IC for H binds
 - 3. IC for L binds

and frontier bends backwards

• Program (\bar{u}_H is parameter here)

$$\max u^L(c_L, y_L)$$

subject to

$$u^H(c_H, y_H) \geq \bar{u}_H$$

ICh, ICl and RC.

• First order conditions: derive same results

1.4 Laffer curve

- back to general case
- When is there a pareto improvement?
- Equivalently: when can we lower taxes and increase tax revenue?
- Given $T_0(Y)$ we get $Y_0(\theta)$ and we have

$$G-e \leq \int T_0(Y_0(\theta))dF(\theta)$$

- Is this Pareto efficient?
- suppose budget holds with equality.
- take *T*₁ prefered to *T*₀
- for feasibility we must have

$$G-e = \int T_0(Y_0(\theta))dF(\theta) \le \int T_1(Y_1(\theta))dF(\theta)$$

where $T_1(Y)$ generates $Y_1(\theta)$

• for improvement it must be that

$$T_1(Y_1(\theta)) \le T_0(Y_1(\theta))$$
 for all θ

and we can always make $T_1(\tilde{Y}) \leq T(\tilde{Y})$ at other points

- hence: (sophisticated) Laffer effect
- Result: there are such Laffer effects (we know from two type case)
- more general results: joint restrictions on...
 - tax schedule T
 - preference U
 - skill distribution F

(note: allocation is implied)

- convert results: joint restrictions on...
 - tax schedule T
 - preference U
 - distribution of output $G(\tilde{Y})$ (where $G(Y(\theta)) = F(\theta)$)

(note: skill distribution is implied)

1.5 IC with a continuum

- need to make IC simpler
 - necessary: local IC + monotonicity
 - also sufficient!
- informally

$$v(\theta) = \max_{\theta'} U(c(\theta'), y(\theta'), \theta) = U(c(\theta), y(\theta), \theta)$$

first order condition ...

$$U_{c}(c(\theta'), y(\theta'), \theta)c'(\theta') + U_{y}(c(\theta'), y(\theta'), \theta)y'(\theta') = 0$$

or rearranging

$$\left[\frac{c'(\theta')}{y'(\theta')} - MRS(c(\theta'), y(\theta'), \theta)\right] U_c(c(\theta'), y(\theta'), \theta)y'(\theta') = 0$$
$$h(\theta, \theta')g(\theta, \theta') = 0$$

- we want this to hold for $\theta = \theta'$ (truth-telling)
- second order condition (informally)

$$h_{\theta'}(\theta,\theta)g(\theta,\theta) + h(\theta,\theta)g_{\theta'}(\theta,\theta) \le 0$$

Now, either *g* or *h* is zero so that we need to worry about the other term. In regions where g = 0, trivially satisfied. In other regions, with y' > 0 and h = 0 we need

$$h_{\theta'}(\theta,\theta) \leq 0$$

but we know that (since $h(\theta, \theta) = 0$ over this region):

$$h_{\theta'}(\theta,\theta) + h_{\theta}(\theta,\theta) = 0$$

and we know that $h_{\theta}(\theta, \theta) > 0$ by the single crossing condition! QED

- stronger result: not just local SOC but actually a max
- note that $g(\theta, \theta') > 0$

– for $\theta' < \theta$ then we have

$$h(\theta, \theta') > h(\theta', \theta') = 0$$

– the reverse is true for $\theta' > \theta$

$$h(\theta, \theta') < h(\theta', \theta') = 0$$

- thus, $\theta' = \theta$ is optimal
- a better approach:
 - change of variables *c*, *y* to *v*, *y*

$$v(\theta) = U(c(\theta), y(\theta), \theta)$$
$$c(\theta) = e(v(\theta), y(\theta), \theta)$$

– let's get the local IC in terms of *v*...

$$v(\theta) - U(c(\theta'), y(\theta'), \theta) \le 0$$

and with equality for $\theta' = \theta$. So $v(\theta) - U(c(\theta'), y(\theta'), \theta)$ is maximized over θ at $\theta = \theta'$. The FOC must be

$$v'(\theta) - U_{\theta} = 0$$

- more generally, an Envelope theorem implies

$$v'(\theta) = U_{\theta}(c(\theta), y(\theta), \theta)$$

or the integral version...

$$v(\theta) = \int^{\theta} U_{\theta}(c(\theta'), y(\theta'), \theta') d\theta'$$

[Milgrom and Segal]

- Result: v,y is incentive compatible (i.e. implies c, y that is IC) iff EC and monotonicity hold
- Duality: Pareto efficiency iff minimize resources subject to delivering $v(\theta)$ or more

2 Pareto Efficient Income Taxation

• Dual for Pareto efficiency:

$$\max_{y,v} \int (y(\theta) - e(v(\theta), y(\theta), \theta)) f(\theta) d\theta$$
$$v'(\theta) = U_{\theta}(e(v(\theta), y(\theta), \theta), y(\theta), \theta)$$
$$v(\theta) \ge \bar{v}(\theta)$$

- where $\{\bar{v}(\theta)\}$ is some parameter
- Remarks:
 - from this we can compute $c(\theta) = e(v(\theta), y(\theta), \theta)$ and then with $c(\theta), y(\theta)$ find retention function R(y) and tax function T(y)
 - in general we will have some multiplier $\zeta(\theta) = \lambda(\theta)f(\theta)/\eta$ on the last constraint (with $\lambda(\theta) = 0$ if the constraint is slack)

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$$\zeta(\theta) = \lambda(\theta) f(\theta) / \eta$$
 and $\bar{v}(\theta)$ related

• Solve

$$\max_{y,v} \{ \int (y(\theta) - e(v(\theta), y(\theta), \theta)) f(\theta) d\theta + \frac{1}{\eta} \int \lambda(\theta) v(\theta) f(\theta) d\theta \}$$

subject to

$$v'(\theta) = U_{\theta}(e(v(\theta), y(\theta), \theta), y(\theta), \theta)$$

• equivalently

$$\frac{1}{\eta} \max_{y,v} \{ \eta \int (y(\theta) - e(v(\theta), y(\theta), \theta)) f(\theta) d\theta + \int \lambda(\theta) v(\theta) f(\theta) d\theta \}$$

which is the Lagrangian that comes out of the problem with objective (Weflare function?)

$$\max_{y,v} \{ \int \lambda(\theta) v(\theta) f(\theta) d\theta \}$$
$$v'(\theta) = U_{\theta}(e(v(\theta), y(\theta), \theta), y(\theta), \theta)$$
$$\int (y(\theta) - e(v(\theta), y(\theta), \theta)) f(\theta) d\theta \le e$$

for some *e* (related to η)

- Utilitarian case is then $\lambda(\theta) = 1$
 - optimal control (*v* is state and *y* is control)
 - FOCs the same with $\lambda(\theta) = 1$ (total multiplier $\zeta(\theta) = f(\theta)/\eta$)
- Form Lagrangian

$$\begin{split} L &\equiv \int (y(\theta) - e(v(\theta), y(\theta), \theta)) f(\theta) d\theta + \frac{1}{\eta} \int \lambda(\theta) v(\theta) f(\theta) d\theta \\ &+ \int \mu'(\theta) v(\theta) + \int \mu(\theta) U_{\theta}(e(v(\theta), y(\theta), \theta), y(\theta), \theta) \end{split}$$

• defining

 $\hat{\mu} = \mu U_c$

• FOCs:

$$-\hat{\mu}'(\theta) - \hat{\mu}(\theta) \frac{\partial MRS(c(\theta), y(\theta), \theta)}{\partial c} y'(\theta) + \zeta(\theta) U_c(c(\theta), y(\theta), \theta) = f(\theta)$$
$$\frac{\tau(\theta)}{1 - \tau(\theta)} f(\theta) = -\hat{\mu}(\theta) \frac{\partial \log MRS(c(\theta), y(\theta), \theta)}{\partial \theta}$$

• Pareto efficiency: multiplier $\zeta(\theta) \ge 0$ so check...

$$-\hat{\mu}'(\theta) - \hat{\mu}(\theta) \frac{\partial MRS(c(\theta), y(\theta), \theta)}{\partial c} y'(\theta) \le f(\theta)$$

$$\frac{\tau(\theta)}{1-\tau(\theta)}f(\theta) = -\hat{\mu}(\theta)\frac{\partial \log MRS(c(\theta), y(\theta), \theta)}{\partial \theta}$$

- take tax system, utility as given...
 - ... hence, take allocation, taxes and utility as given
- observe distribution of output: infer distribution of skills (more later)
- second equation gives $\hat{\mu}$ uniquely, first inequality is restriction
- note: anything goes: there exists an *f* such that condition is met given *U* and *T*
- given *f* and *U*: many *T* are inefficient, many efficient
- tax at top and bottom: $\tau(\bar{\theta}) \leq 0$ and $\tau(\underline{\theta}) \geq 0$
- Utilitarian: set $\zeta(\theta) = f(\theta)/\eta$ and solve ODEs:

$$-\hat{\mu}'(\theta) - \hat{\mu}(\theta) \frac{\partial MRS(c(\theta), y(\theta), \theta)}{\partial c} y'(\theta) + \frac{1}{\eta} f(\theta) U_c(c(\theta), y(\theta), \theta) = f(\theta)$$
$$\frac{\tau(\theta)}{1 - \tau(\theta)} f(\theta) = -\hat{\mu}(\theta) \frac{\partial \log MRS(c(\theta), y(\theta), \theta)}{\partial \theta}$$

along with $\mu(\underline{\theta}) = \mu(\overline{\theta}) = 0$ [since state *v* is free at the boundaries; or note the special FOCs for them derived in recitation]

- a bit more involved
- can be done numerically
- special cases: *U* quasi-linear in *c* (so that $\frac{\partial MRS(c(\theta), y(\theta), \theta)}{\partial c} = 0$)
- check Diamond and Saez papers
- Saez identification: observe output distribution H...

$$F(\theta) = H(y(\theta))$$
$$f(\theta) = h(y(\theta))y'(\theta)$$

- given *U* and *T* we can compute $y(\theta)$ and hence $y'(\theta)$...

$$y'(\theta) = \frac{-\frac{\partial \log MRS(c(\theta), y(\theta), \theta)}{\partial \theta}}{\frac{1}{\varepsilon_w^* Y} + \frac{T''(Y)}{1 - T'(Y)}}$$

…nicer to solve for y'(θ) in terms of local conditions (some algebra later; see Recitation)

$$\begin{aligned} &-\hat{\mu}'(\theta) - \hat{\mu}(\theta) \frac{\partial MRS(c(\theta), y(\theta), \theta)}{\partial c} \le h(y(\theta)) \\ &\hat{\mu}(\theta) = \frac{T'(y)}{1 - T'(y)} \varepsilon_w^*(Y) Y \frac{h(y(\theta))}{1 + Y \varepsilon_w^*(Y) \frac{T''(Y)}{1 - T'(Y)}} \end{aligned}$$

- (utilitarian case: $-\hat{\mu}'(\theta) \hat{\mu}(\theta) \frac{\partial MRS(c(\theta), y(\theta), \theta)}{\partial c} = (1 \lambda U_c)h(y(\theta)))$
- Saez defines the "virtual density"...

$$h^{*}(Y) = \frac{h(y)}{1 + Y\varepsilon_{w}^{*}(Y)\frac{T''(Y)}{1 - T'(Y)}} = \frac{h(y)}{\Phi(y)}$$

• after subsituting...

$$\frac{\tau}{1-\tau}\frac{\varepsilon_w^*}{\Phi}\left(-\frac{d\log\frac{\tau}{1-\tau}}{d\log y}-\frac{d\log h^*}{d\log Y}-1-\frac{d\log\varepsilon_w^*}{d\log Y}-\frac{\partial MRS}{\partial c}\frac{1}{y}\right) \le 1$$

- think through role of each term
- intuition for inefficient tax: Laffer argument
- generalizes: tax at top and bottom: $\tau(\bar{\theta}) \leq 0$ and $\tau(\underline{\theta}) \geq 0$

$$\frac{d\log h^*}{d\log Y} = -\infty$$
 or $\frac{d\log h^*}{d\log Y} = \infty$

- Discussion:
 - 1. anything goes again: exists h^* given U and T
 - 2. linear tax optimal? Yes, depends on distribution.
 - 3. maximum level of asymptotic tax rate (many terms cancel)
 - 4. connection with Rawlsian optimum
- observable characteristics: Differential taxation?
 - Pareto efficient to ignore? Yes, in some cases...... new condition is average of previous condition

- Pareto improvement to differentiate? Yes, in some cases...

... if previuos condition is violated for some group

3 Extensive Margin Model

- Diamond (1980): nonlinear taxation with extensive margin (no intensive margin).
- as before, preferences are

$$U(c, Y, \theta)$$

- but now
 - assume only two possible levels of *Y* for each θ

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\{0, Y(\theta)\}
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- $Y(\theta)$ continuous and increasing
- $\theta \in [0,\infty)$
- -Y(0) = 0
- assume some measure *N* of agents simply cannot work
- for agent θ to prefer work we require

$$U(c(\theta), Y(\theta), \theta) \ge U(b, 0, 0)$$

- incentive constraint
 - like before, compares allocation intended for θ to others'
 - previously:
 - * compared to all other bundles
 - * binding were neighbours (with single crossing assumptions)
 - now: relevant binding constraint is always allocation meant for $\theta = 0$ i.e. Y = 0, so binding constraint skips neighbours, in this sense this is a violation of single crossing
- it might be optimal to make some agents that are capable of working not work, but we will assume instead that we make them all work

• Planning Problem:

$$\max\left\{NU(b,0,\theta) + \int U(c(\theta),Y(\theta),\theta)f(\theta)d\theta\right\}$$

s.t.

$$Nb + \int (c(\theta) - Y(\theta))f(\theta)d\theta \le e$$
$$U(c(\theta), Y(\theta), \theta) \ge U(b, 0, 0)$$

• first order conditions:

$$U_b(b,0,0) = \lambda - \frac{1}{N} \int \mu(\theta) d\theta$$
$$U_c(c(\theta), Y(\theta), \theta) = \lambda + \mu(\theta)$$

and $\mu(\theta) \ge 0$

$$\mu(\theta)[U(c(\theta), Y(\theta), \theta) - U(b, 0, 0)] = 0$$

as well as both constraints holding.

• combining the conditions gives:

$$U_c(c(\theta), Y(\theta), \theta) \leq U_b(b, 0, 0) + \frac{1}{N} \int \mu(\theta) d\theta < U_b(b, 0, 0)$$

as long as the work constraint binds for some agents

• with separable utility $u(c) - v(Y, \theta)$ this implies immediately that

$$c(\theta) > b$$

for all θ and that

$$\lim_{\theta \to 0} c(\theta) > b$$

- indeed with separable utility we must have μ(θ) = 0 and U(c(θ), Y(θ), θ) > U(b, 0, 0) for low enough θ
- nice case has preferences independent of θ :

$$u(c, Y, \theta) = U(c, Y)$$

• then easy to see that defining the equalizing difference

$$U(c^{e}(Y),Y) = U(b,0)$$

we have that optimal consumption is

$$c^*(Y) = \max\{c^e(Y), \bar{c}\}$$

where $\bar{c} \equiv (u')^{-1}(\lambda) > b$

• conclusions:

- we get an upward discontinuity in $c(\theta)$
- more general: symptomatic that marginal tax may be negative
- possible odd result: consumption $c(\theta)$ may not be monotone (could be fixed with additional assumptions) (i.e. marginal taxes may be higher than 100%)
- comments:
 - overall:
 - * with Utilitarian, less sharp restrictions on marginal taxes Mirrlees model, i.e. here they can be negative or higher than 100%.
 - * but not clear if less implications for Pareto efficient.
 - Here: some people can work, others suffer infinite disutility (i.e. can't work).
 Diamond's paper has a more general joint distribution between skill and labor disutility. Optimum then needs to determine how many people work, at each skill level.
 - Saez combines intensive and extensive margin.
- Planning problem

$$\max\left\{\int\int_{n^{*}(\theta)}U(b,0,\theta)dnd\theta+\int\int^{n^{*}(\theta)}U(c(n),Y(n),\theta)f(\theta,n)dnd\theta\right\}$$

s.t.

$$Nb + \int (c(\theta) - Y(\theta))f(\theta)d\theta \le e$$
$$U(c(\theta), Y(\theta), \theta) \ge U(b, 0, 0)$$

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