## Problems: Curl in 3D

**1**. Let  $\mathbf{F} = \langle x, y, z \rangle$ . Calculate and interpret curl $\mathbf{F}$ . Answer:

$$\operatorname{curl} \mathbf{F} = \nabla \times \mathbf{F}$$
$$= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x & y & z \end{vmatrix}$$
$$= \langle 0, 0, 0 \rangle.$$

We can interpret **F** as a velocity field in which particles race away from (0, 0, 0) with speed equal to their distance from the origin. Because curl **F** = **0**, there is no rotational component in this field.

This makes sense. If we place a tiny paddle wheel at the point (1,0,0), the torque about the axis from the force on a paddle just below the x-axis is exactly cancelled by the one symmetrically placed just above the x-axis. Since all the forces all the way around the wheel come in such pairs the net torque is 0 and the wheel will not start to spin. A similar argument holds for all other points in the plane except the origin. At the origin there is no force on any of the paddles, so the wheel doesn't spin.

**2**. Let  $\mathbf{F} = \langle y, 0, 0 \rangle$ . Calculate and interpret curl $\mathbf{F}$ .

Answer:

$$\operatorname{curl} \mathbf{F} = \nabla \times \mathbf{F}$$
$$= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & 0 & 0 \end{vmatrix}$$
$$= \langle 0, 0, -1 \rangle.$$

We can interpret  $\mathbf{F}$  as a velocity field in which particles move away from the *yz*-plane with speed equal to their *y* coordinate. A tiny paddle wheel placed in this field with its axle pointing in the  $\mathbf{k}$  direction will spin clockwise. Applying the right hand rule confirms the calculation that this field has a negative rotational component.

A paddle wheel placed with its axle pointing in the **i** direction will be completely unaffected by the velocity field, while the forces on the paddles of a wheel with its axle pointing in the **j** direction will cancel, as in problem 1. MIT OpenCourseWare http://ocw.mit.edu

18.02SC Multivariable Calculus Fall 2010

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