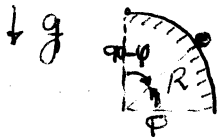


Example (1)



Question: angle of departure
Point of departure is the point where the reaction force acting on particle becomes zero.

FBD



Linear momentum principle $\dot{p} = F$

From geometry $r = (\cos\phi \mathbf{e}_1 + \sin\phi \mathbf{e}_2)R$

$$v = \dot{r} = (-\sin\phi \dot{\phi} \mathbf{e}_1 + \cos\phi \dot{\phi} \mathbf{e}_2)R$$

$$a = \dot{v} = \{-\cos\phi \dot{\phi}^2 - \sin\phi \ddot{\phi}\} \mathbf{e}_1 + \{-\sin\phi \dot{\phi}^2 + \cos\phi \ddot{\phi}\} \mathbf{e}_2 \} R$$

$$\Rightarrow \dot{p} = m\dot{v} = ma = mR(-\cos\phi \dot{\phi}^2 - \sin\phi \ddot{\phi}) \mathbf{e}_1 + mR(-\sin\phi \dot{\phi}^2 + \cos\phi \ddot{\phi}) \mathbf{e}_2 = \underline{N} + mg \mathbf{j}$$

Project in the direction of \mathbf{e}_N
multiply by $\mathbf{e}_N = \cos\phi \mathbf{e}_1 + \sin\phi \mathbf{e}_2$

$$-mR\dot{\phi}^2 = N - mg\sin\phi$$

At the point of departure $N=0$

$$\Rightarrow R\dot{\phi}_*^2 = g\sin\phi_*$$

to obtain another equation for $(\phi_*, \dot{\phi}_*)$, use work-Energy principle

$$W_{12} = T_2 - T_1$$

$$W_{12} = \int_1^2 F \cdot dr = \int_1^2 N dr + \int_1^2 mg dr$$

$$F = -\nabla V$$

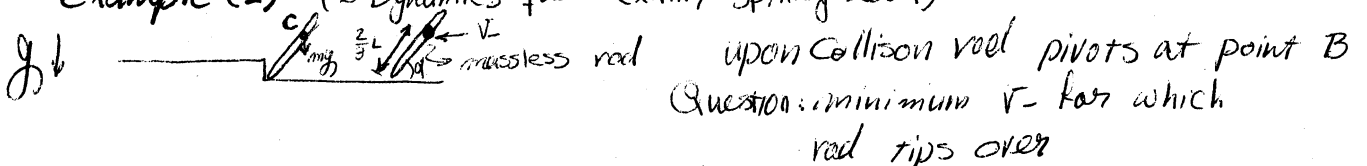
Since N doesn't do any work ($N \perp v$) \Rightarrow System is Conservative $T + V = \text{const}$

$$0 + mgR = \frac{1}{2} m |v|^2 + mgR \sin\phi$$

$$|v| = \left| \frac{d}{dt} (R(\frac{R}{2} - \theta)) \right| = R^2 \dot{\phi}^2$$

$$\Rightarrow \frac{1}{2} R^2 \dot{\phi}_*^2 = gR(1 - \sin\phi_*) \quad \text{both} \quad \Rightarrow \sin\phi_* = \frac{2}{3} \Rightarrow \phi_* = 41.81^\circ$$

Example (2) (\approx Dynamics qual exam, Spring 2004)



upon collision rod pivots at point B
Question: minimum v for which rod tips over

part 1: Collision itself ($t_- \rightarrow t_+$)

Forces at B are unknown \Rightarrow use angular momentum principle w.r.t B

$$\dot{H}_B + \vec{r}_{BC} \times \vec{P} - M_B = \vec{r}_{BC} \times (m\vec{g})$$

Integrate from t_- to t_+

$$H_B(t_+) - H_B(t_-) = \int_{t_-}^{t_+} \vec{r}_{BC} \times (m\vec{g}) dt \neq 0$$

$$\Rightarrow H_B(t_-) \neq H_B(t_+)$$

$\Rightarrow H_B$ is conserved during collision

$$H_B(t_-) = \vec{r}_{BC} \times \vec{P}(t_-) = \vec{r}_{BC} \times (m\vec{v}_-) = \left(\frac{2L}{3} \hat{z}\right) m v_- \hat{z}$$

$$H_B(t_+) = \vec{r}_{BC} \times \vec{P}(t_+) = \vec{r}_{BC} \times (m\vec{v}_+) = \frac{2L}{3} m v_+ \hat{z}$$

$$\Rightarrow v_+ = v_- \hat{z}$$

Part 2: Rotation

work-energy principle $W_{12} = T_2 - T_1$

$$W_{12} = W_{12}^{\text{gravity}} + W_{12}^{\text{reaction}} \quad (\text{B does not move})$$

\Rightarrow motion is conservative $W_{12} = V_1 - V_2$

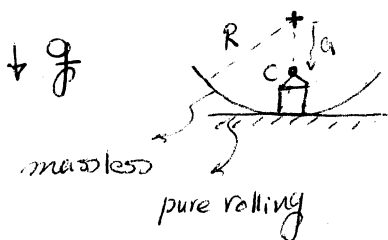
$$T + V = \text{const}$$

$$\frac{1}{2} m v^2 + m g \frac{2L}{3} \sin \alpha = 0 + m g \frac{2L}{3} \quad \text{critical case}$$

$$v_+^2 = \frac{4L}{3} g (1 - \sin \alpha)$$

$$v_- = \sqrt{\frac{4Lg}{3} \left(\frac{1}{\sin \alpha} - 1 \right)}$$

Example (3)



Question: equations of motion

- Constraint force
- frequency of small oscillations