# Single-stage, multiple-part-type systems

Lecturer: Stanley B. Gershwin

- Setup: A setup change occurs when it costs more to make a Type *j* part after making a Type *i* part than after making a Type *j* part.
- Examples:
  - \* Tool change (when making holes)
  - \* Die change (when making sheet metal parts)
  - ★ Paint color change
  - Replacement of reels of components, when populating printed circuit cards

## Costs

- Setup costs can include
  - Money costs, especially in labor. Also materials.
    Time, in loss of capacity and delay.
- Some machines create scrap while being adjusted during a setup change.
- Setups motivate *lots* or *batches:* a set of parts that are processed without interruption by setups.

## Costs

## • Problem:

- Large lots lead to large inventories and long lead times.
- \* Small lots lead to frequent setup changes.
- Reduction of setup time has been a very important trend in modern manufacturing.

## **Flexibility**

- Flexibility: a widely-used term whose meaning diminishes as you look at it more closely. (This may be the definition of a <u>buzzword</u>.)
- *Flexibility:* the ability to make many different things ie, to operate on many different parts.
- Agility is also sometimes used.

## **Flexibility**

## Which is more flexible?

- A machine that can hold 6 different cutting tools, and can change from one to another with zero setup time.
- A machine that can hold 25 different cutting tools, and requires a 30-second setup time.

## Which is more flexible?

- A final assembly line that can produce all variations of 6 models of cars, and can produce 100 cars per day.
- A final assembly line that can produce all variations of 1 model at 800 cars per day?

## Setup Machines vs Batch Machines

- A machine has setups when there are costs or delays associated with changing part types. Machines that require setups may make one or many parts at a time.
- A machine operates on batches of size n if it operates on up to n parts simultaneously each time it does an operation. Batch machines may or may not operate on different part types. If they do, they may or may not require setup changes. (Also, the batches may or may not be homogeneous.)
  - *★ Examples:* Ovens and chemical chamber operations in semiconductor manufacturing; chemical processing of liquids.

## **Loss of Capacity**

## Assume

- there is one setup for every Q parts (Q=lot size),
- the setup time is S,
- the time to process a part is au.

Then the time to process Q parts is  $S + Q\tau$ . The average time to process one part is  $\tau + S/Q$ .

If the demand rate is *d* parts per time unit, then the demand is feasible only if

Loss of Capacity

$$au + S/Q < 1/d \quad ext{or} \quad d < rac{Q}{S+Q au} = rac{1}{ au + S/Q} < rac{1}{ au}$$

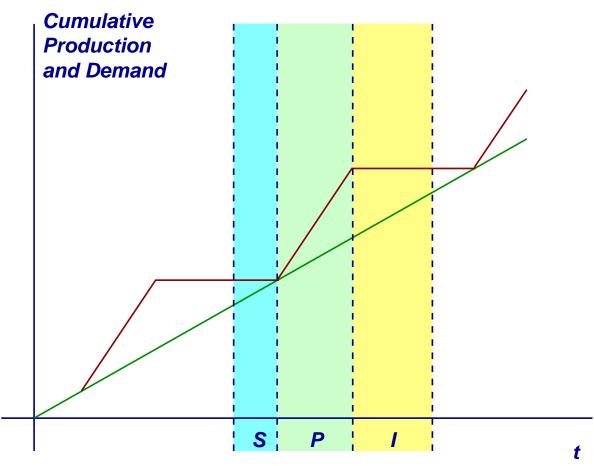
This is not satisfied if S is too large or Q is too small.

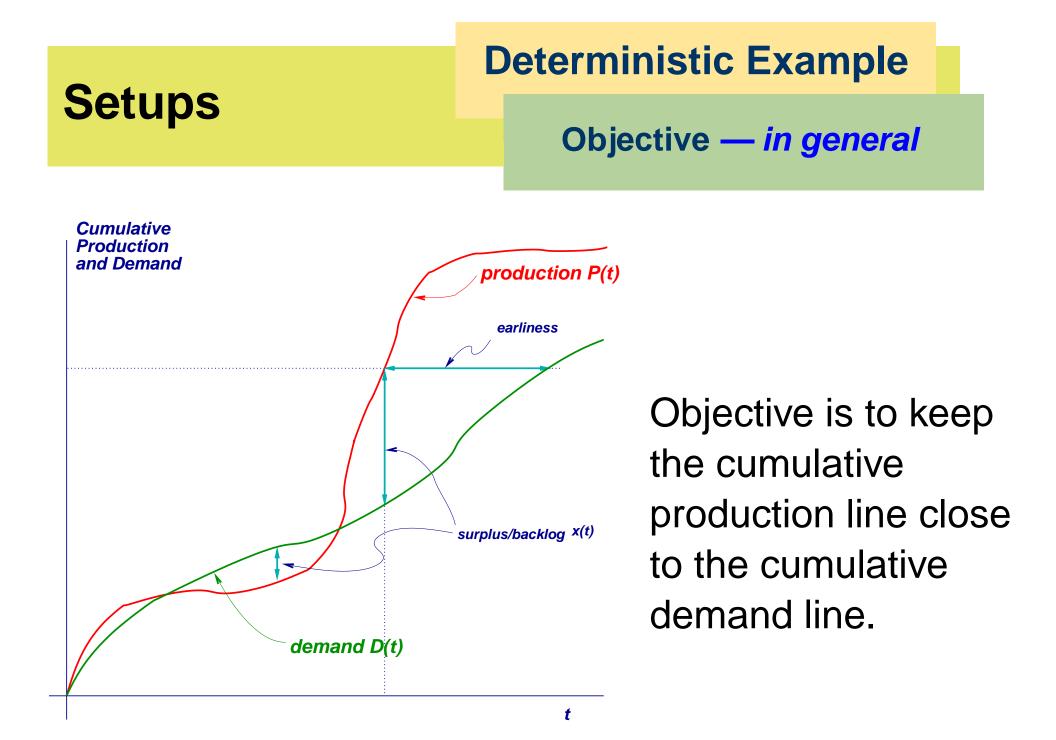
- Focus on a single part type (simplification!)
- Short time scale (hours or days).
- Constant demand.
- Deterministic setup and operation times.
- Setup/production/(idleness) cycles.
- *Policy:* Produce at maximum rate until the inventory is enough to last through the next setup time.

# **Setups**

Cycle:

- S = setup period for the part type
- P = period the machine is operating on the part type
- *I* = period the machine is making or setting up for *other* parts, or idle





# **Setups**

## Cycle:

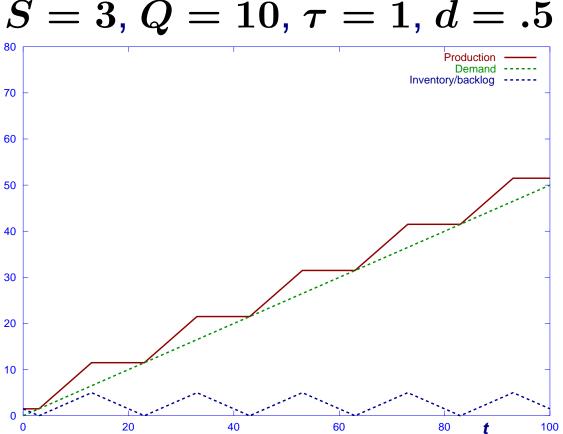
- Setup period. Duration: S. Production: 0. Demand: Sd. Net change of surplus, ie of P-D is  $\Delta_S = -Sd$ .
- Production period. Duration:  $t = Q\tau$ . Production: Q. Demand: td. Net change of P - D is  $\Delta_P = Q - td = Q - Q\tau d = Q(1 - \tau d).$

- Idleness period (for the part we focus on). Duration: I. Production: 0. Demand: Id. Net change of P - D is  $\Delta_I = -Id$ .
- Total (desired) net change over a cycle: 0.
- Therefore, net change of P-D over whole cycle is  $\Delta_S+\Delta_P+\Delta_I=-Sd+Q(1- au d)-Id=0.$

- Since  $I \geq 0$ ,  $Q(1 \tau d) Sd \geq 0$ .
- If I=0, Q(1- au d)=Sd.
- If  $\tau d > 1$ , net change in P D will be negative.

## **Deterministic Example**

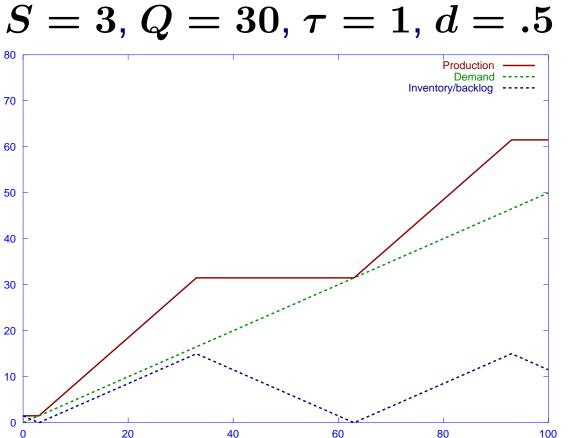
#### **Production & inventory history**



- Production period duration =  $Q\tau = 10$ .
- Idle period duration = 7.
- Total cycle duration = 20.
- Maximum inventory is Q(1- au d)=5.

## **Deterministic Example**

#### Not frequent enough

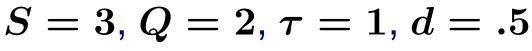


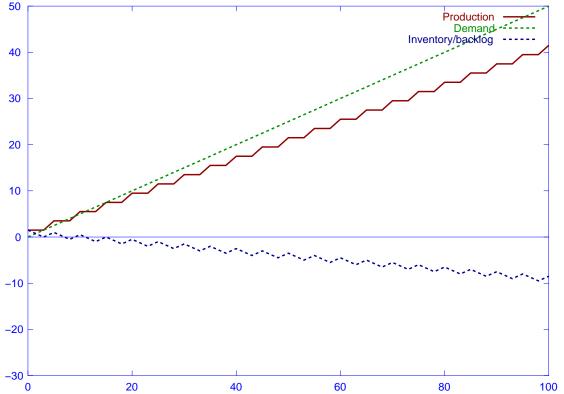
- Production period duration =  $Q\tau = 30$ .
- Idle period duration = 27.
- Total cycle duration = 60.

• Maximum inventory is Q(1- au d)=15.

## **Deterministic Example**

#### **Too frequent**



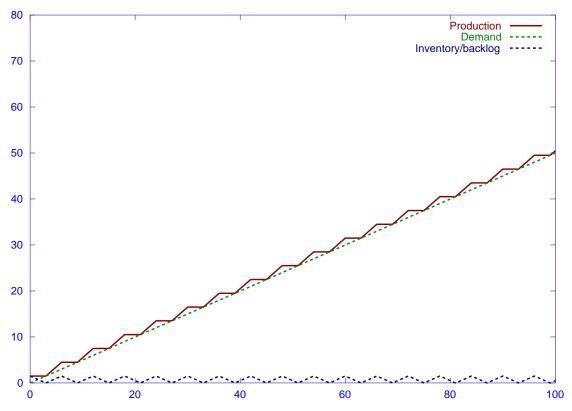


- Batches too small demand not met.
- ullet Q(1- au d)-Sd= -0.5
- Backlog grows.
- Too much capacity spent on setups.

## **Deterministic Example**

#### **Just right!**

#### $S=3,\,Q=3,\, au=1,\,d=.5$

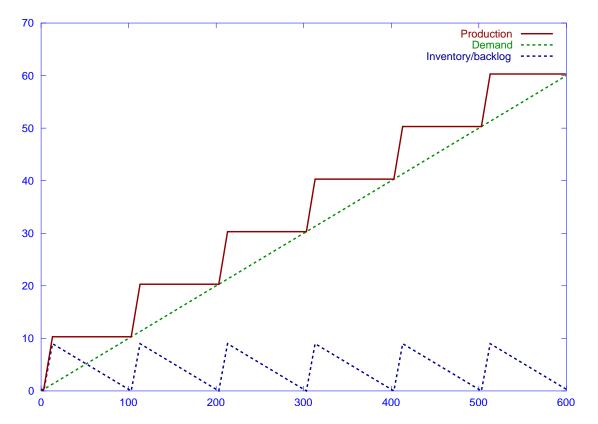


- Small batches small inventories.
- Maximum inventory is Q(1- au d)=1.5.

## **Deterministic Example**

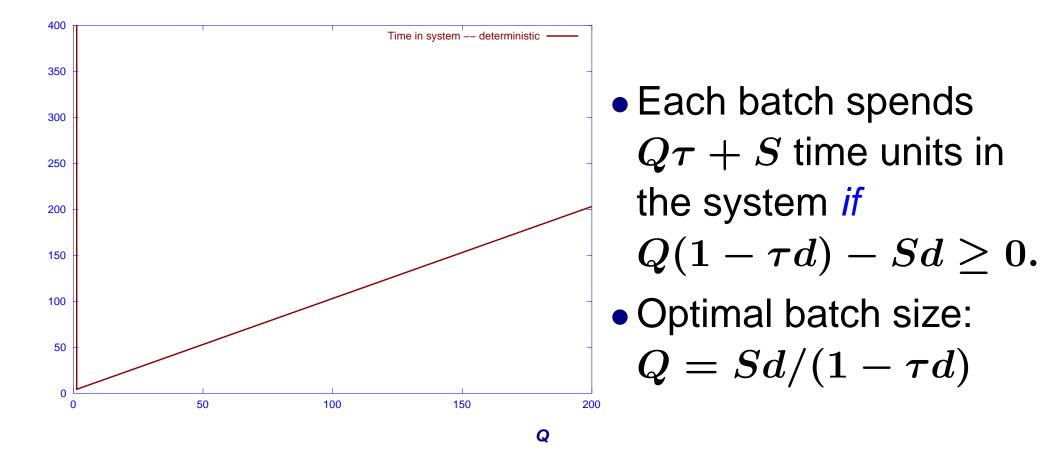
#### **Other parameters**





## **Deterministic Example**

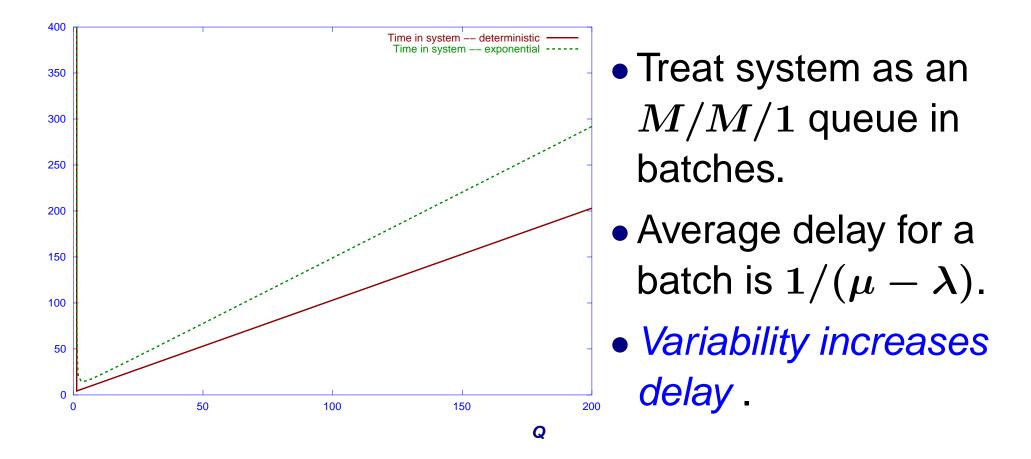
#### Time in the system



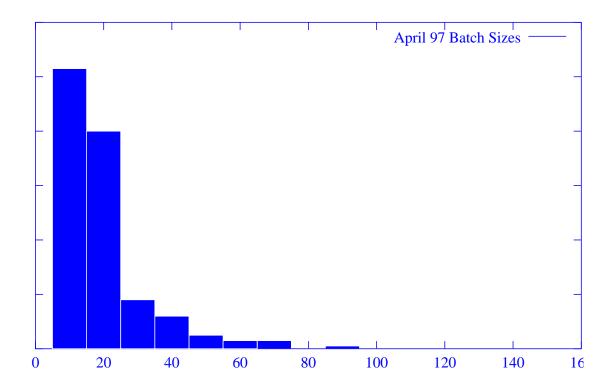
## **Stochastic Example**

- Batch sizes equal (Q); processing times random.
  ★ Average time to process a batch is Qτ + S = 1/μ.
  Random arrival times (exponential inter-arrival times)
  ★ Average time between arrivals of batches is Q/d = 1/λ.
- Infinite buffer for waiting batches

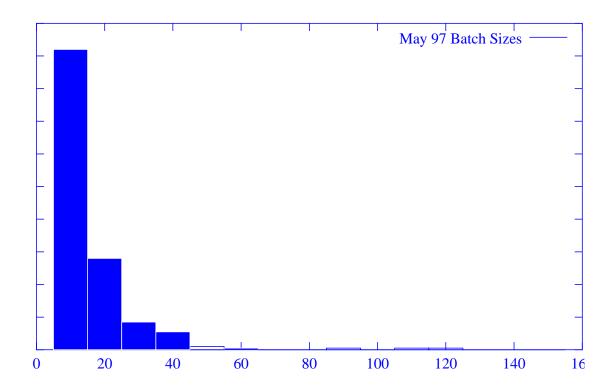
## **Stochastic Example**



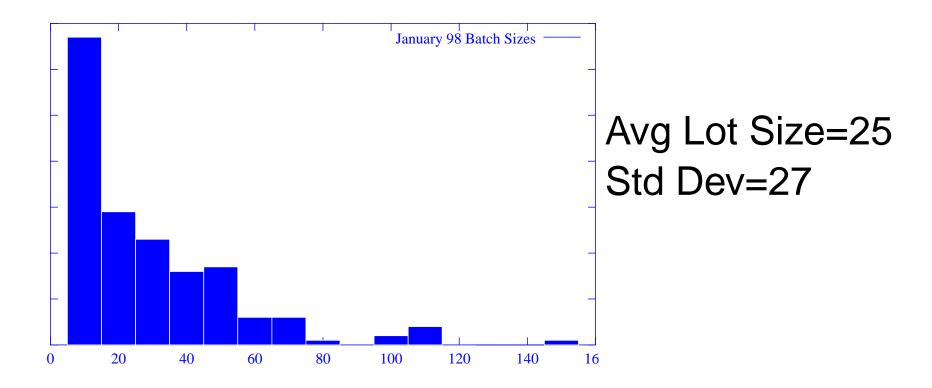
# Batch size data from a factory



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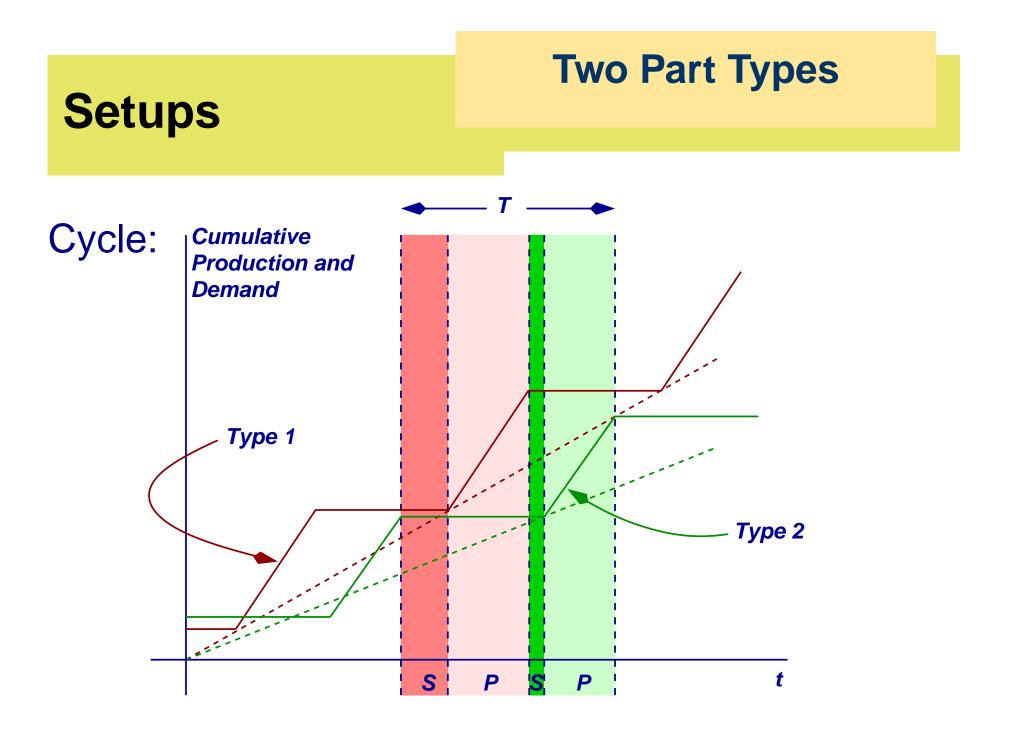


## • Assumptions:

\* Cycle is produce Type 1, setup for Type 2, produce Type 2, setup for Type 1.

**Two Part Types** 

- **\*** Unit production times:  $\tau_1, \tau_2$ .
- $\star$  Setup times:  $S_1, S_2$ .
- **\*** Batch sizes:  $Q_1, Q_2$ .
- **\star** Demand rates:  $d_1, d_2$ .
- ⋆ No idleness.



### **Two Part Types**

# **Setups**

Let T be the length of a cycle. Then  $S_1+ au_1Q_1+S_2+ au_2Q_2=T$  To satisfy demand,

$$Q_1=d_1T; \quad Q_2=d_2T$$

This implies

$$T = rac{S_1 + S_2}{1 - ( au_1 d_1 + au_2 d_2)}$$

## **Two Part Types**

- $\tau_i d_i$  is the fraction of time that is devoted to producing part *i*.
- $1 (\tau_1 d_1 + \tau_2 d_2)$  is the fraction of time that is *not* devoted to production.
- We must therefore have  $\tau_1 d_1 + \tau_2 d_2 < 1$ . This is a *feasibility condition*.

## **Multiple Part Types**

# **Setups**

- New issue: Setup sequence .
  - \* In what order should we produce batches of different part types?
- $S_{ij}$  is the setup time (or setup cost) for changing from Type i production to Type j production.

• Problem:

 $\star$  Select the setup sequence  $\{i_1, i_2, ..., i_n\}$  to minimize  $S_{i_1i_2} + S_{i_2i_3} + ... + S_{i_{n-1}i_n} + S_{i_ni_1}$ .

## **Multiple Part Types**

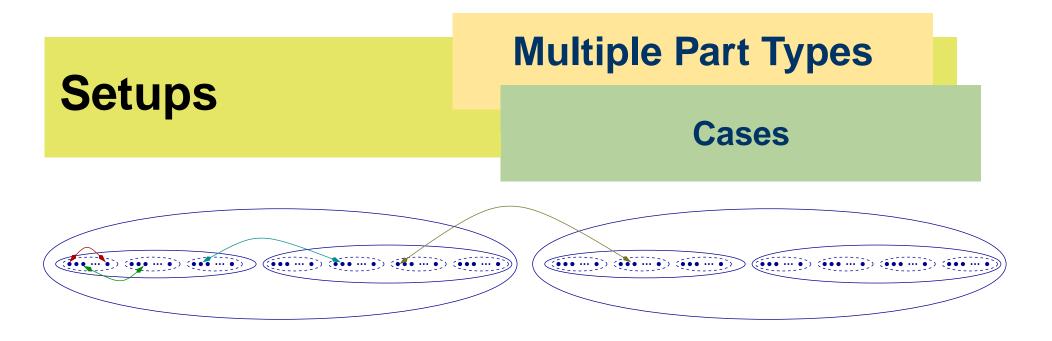
Cases

- Sequence-independent setups:  $S_{ij} = S_j$ . Sequence does not matter.
- Sequence-dependent setups: traveling salesman problem.

## **Multiple Part Types**

#### Cases

- Paint shop: *i* indicates paint color number.
- $S_{ij}$  is the time or cost of changing from Color i to Color j.
- If i > j, i is darker than j and  $S_{ij} > S_{ji}$ .



- Hierarchical setups.
- Operations have several attributes.
- Setup changes between some attributes can be done quickly and easily.
- Setup changes between others are lengthy and expensive.

## **Dynamic Lot Sizing**

# **Setups**

- Wagner-Whitin (1958) problem
- Assumptions:
  - \* Discrete time periods (weeks, months, etc.);

t = 1, 2, ..., T.

- $\star$  Known, but non-constant demand  $D_1$ ,  $D_2$ , ...,  $D_T$ .
- \* Production, setup, and holding cost.
- ★ Infinite capacity.

## **Dynamic Lot Sizing**

#### **Other notation**

- $c_t$  = production cost (dollars per unit) in period t
- $A_t$  = setup or order cost (dollars) in period t
- $h_t$  = holding cost; cost to hold one item in inventory from period t to period t + 1
- $I_t$  = inventory at the end of period t the state variable
- $Q_t$  = lot size in period t the decision variable

### **Dynamic Lot Sizing**

**Problem** 

minimize  $\sum_{t=1}^{T} (A_t \delta(Q_t) + c_t Q_t + h_t I_t)$ 

(where  $\delta(Q) = 1$  if Q > 0;  $\delta(Q) = 0$  if Q = 0)

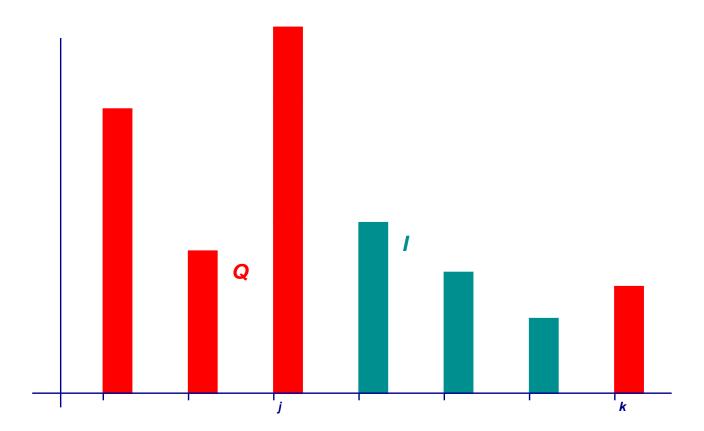
subject to

 $ullet I_{t+1} = I_t + Q_t - D_t$  $ullet I_t \geq 0$ 

### **Dynamic Lot Sizing**

#### **Wagner-Whitin Property**

### Characteristic of Solution:



### **Dynamic Lot Sizing**

**Wagner-Whitin Property** 

Characteristic of Solution:

- Either  $I_t = 0$  or  $Q_{t+1} = 0$ . That is, produce only when inventory is zero. Or,
  - \* If we assume  $I_j = 0$  and  $I_k = 0$  (k > j) and  $I_t > 0, t = j + 1, ..., k,$ \* then  $Q_j > 0, Q_k > 0$ , and  $Q_t = 0, t = j + 1, ..., k.$

### **Dynamic Lot Sizing**

#### **Wagner-Whitin Property**

### Then

• 
$$I_{j+1} = Q_j - D_j,$$
  
•  $I_{j+2} = Q_j - D_j - D_{j+1}, ...$   
•  $I_k = 0 = Q_j - D_j - D_{j+1} - ... - D_k$ 

Or,  $Q_j = D_j + D_{j+1} + ... + D_k$ 

which means produce enough to exactly satisfy demands for some number of periods, starting now.

## **Dynamic Lot Sizing**

**Wagner-Whitin Property** 

- This is not enough to determine the solution, but it means that the search for the optimal is limited.
- It also gives a qualitative insight.

### **Real-Time Scheduling**

# **Setups**

- *Problem:* How to decide on batch sizes (ie, setup change times) in response to events.
- Issue: Same as before.
  - Changing too often causes capacity loss; changing too infrequently leads to excess inventory and lead time.

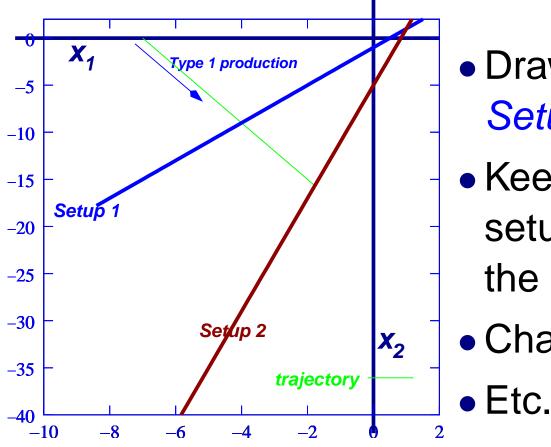
**Real-Time Scheduling** 

**One Machine, Two Part Types** 

Model:

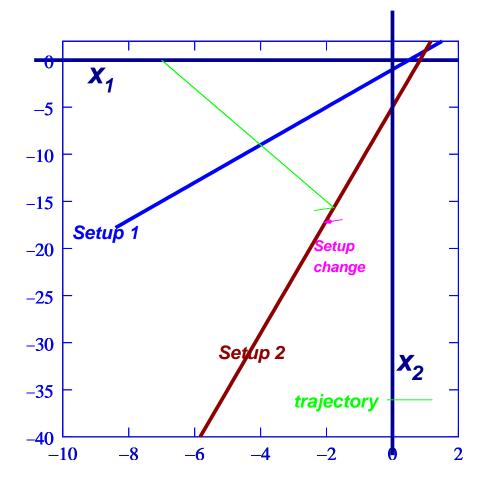
- $d_i$  = demand rate of Type i
- $\mu_i = 1/\tau_i$  = maximum production rate of Type i
- S = setup time
- $u_i(t)$  = production rate of Type i at time t
- $x_i(t)$  = surplus (inventory or backlog) of Type i•  $\frac{dx_i}{dt} = u_i(t) - d_i, i = 1, 2$

### **Real-Time Scheduling**

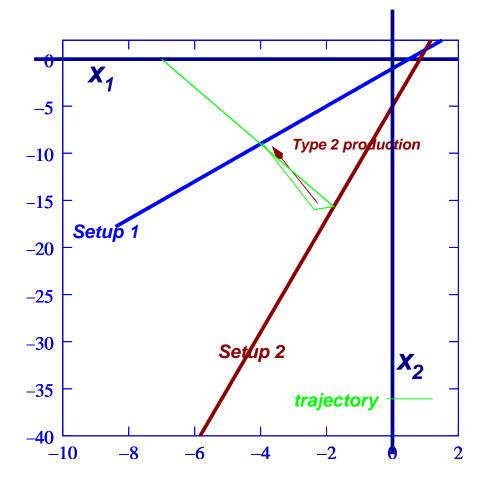


- Draw two lines, labeled Setup 1 and Setup 2.
- Keep the system in setup i until x(t) hits the Setup j line.
- Change to setup j.

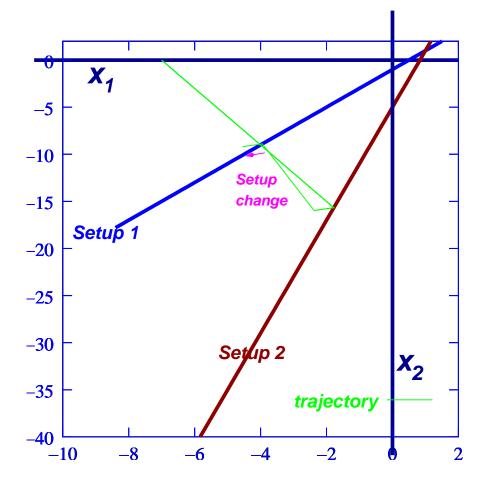
### **Real-Time Scheduling**



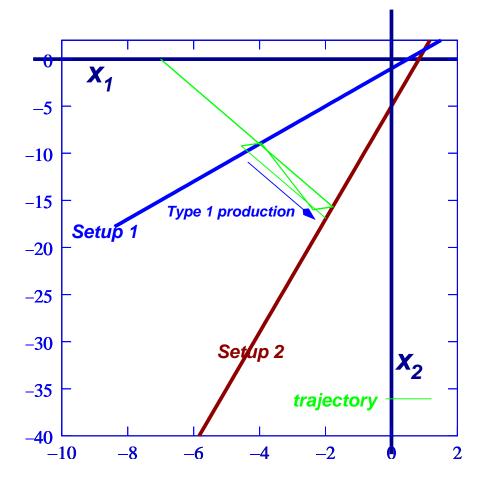
### **Real-Time Scheduling**



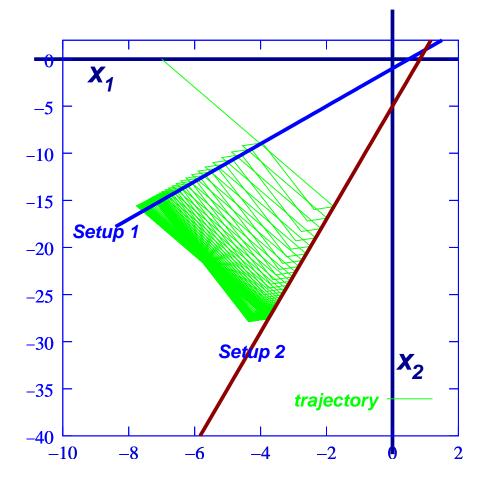
### **Real-Time Scheduling**



### **Real-Time Scheduling**



### **Real-Time Scheduling**



### **Real-Time Scheduling**

- In this version, batch size is a function of time.
- Also possible to pick parallel boundaries, with an upper limit. Then batch size is constant until upper limit reached.

### **Real-Time Scheduling**

**Heuristic: Corridor Policy** 

Two possibilities (for two part types):

- Converges to limit cycle only if demand is within capacity, ie if  $\sum_i \tau_i d_i < 1$ .
- Diverges if
  - \* demand is not within capacity, or
  - \* corridor boundaries are poorly chosen.

### **Real-Time Scheduling**

**More Than Two Part Types** 

Three possibilities (for more than two part types):

- Limit cycle only if demand is within capacity,
- Divergence if
  - \* demand is not within capacity, or
  - corridor boundaries are poorly chosen.
- Chaos if demand is within capacity, and corridor boundaries chosen ... not well?

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