## Experiment 06: Work, Energy and the Harmonic Oscillator



# Goals

□ Investigate the work-mechanical energy theorem.

Observe how forms of mechanical energy are converted from one to another and lost by non-conservative work.

Study the behavior of a simple harmonic motion with a high quality low-loss spring.

## Equipment setup





- □ Use the heavy spring on the force sensor.
- □ Put two 250g weights in the cart.
- Clip motion sensor to other end of track, and support it on a piece of 2x4.

## Starting DataStudio

□ Create a new experiment.

- □ Plug force and motion sensors into the 750 and
- $\Box$  drag their icons to inputs in the Setup window.



#### Double-click the Force Sensor icon.

### Force Sensor

Sensor Properties	Sensor Properties	×
General Measurement Calibration	General Measurement Calibration	
Force Sensor Model: CI-6537, CI-6746	Current Reading Voltage: 0.003 Value: 0.02 High Point Voltage: Value: 50.00 Take Reading	Low Point Voltage: -8.000 Value: -50.00 Take Reading
Sample Rate 500 Hz - + © Fast (> 1 Hz) © Slow (< 1 Hz)	Name: Force, Ch A (N)	Sensitivity: Low (1x)
<ul> <li>Slow Force Changes (Spring Tests)</li> <li>Fast Force Changes (Collisions)</li> </ul>	Range: Units: -8.00 to 8.00 N	Accuracy: 0.01
OK Cancel Help	OK Ca	ancel Help

□ Set Sample Rate to 500Hz and Sensitivity to Low.

Double-click the Motion Sensor Icon.

### **Motion Sensor**

Sensor Properties	Sensor Properties	×
General       Measurement       Motion Sensor         Measurement List           ✓ Acceleration, Ch 1&2 (m/s/s)           Motion Timer, Ch 1&2 (Time)           ✓ Position, Ch 1&2 (m)           ✓ Velocity, Ch 1&2 (m/s)	General Measurement Motion Sensor Calibration Distance: 0.825 m Calibrate Current Distance: 0.825 m Trigger Rate: 60	Speed of Sound: 341.3 m/s Max Distance: 1.00 m Min Distance: CI-6521A 0.50 m
Range: Unit: Accuracy: 0.100 to 8.000 m 1.000E-3		CI-6742 0.15 m
OK Cancel Help	ОК С.	ancel Help

□ Ensure to have Acceleration, Position and Velocity checked

□ Set Trigger Rate to 60Hz and

□ calibrate distance to cart when it is resting against the spring.



## Sampling Options



Stop after 10s!

#### Measurement Results



Position vs. Time: Measure maximum heights either side of 2<sup>nd</sup> bounce, calculate loss of potential energy, and friction force. Enter in table!



Force vs. Time: Expand force peak around 2<sup>nd</sup> bounce.

### Finding Acceleration Up & Down





Linear fit to find  $a_{up}$ 





Linear fit to find  $a_{down}$ 

## Analysis Force Peak



User-Defined Fit to A\*sin(2\*pi(x-C)/T)

## Harmonic Oscillator



Unclip motion sensor, raise the force sensor end of track



Attach spring to plunger on cart with a binder clip and to the hook on force sensor.

Add two 250g weights in the cart.

Place motion sensor on table touching other end of track.

Set Delayed Start and Auto Stop.

### Harmonic Oscillator Results



Position vs. Time: Measure the period, and calculate spring constant k from M = 0.75 kg.



Force vs. Time.

Make a plot of force vs. position.

### Lissajous Patterns



Force vs. Position: Find k from a Linear Fit.

Velocity vs. Position.

## **Rubber Band Spring - Optional**



Position vs. Time: Note increased damping.



Force vs. Position. Not linear.

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