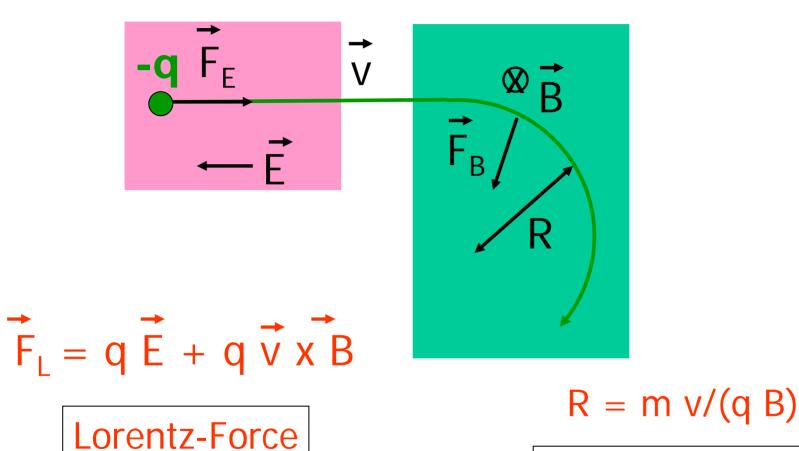
# **Electricity and Magnetism**

- Recap
  - Forces in B-Field
- Today
  - Sources of B-Field
    - Law of Biot-Savart
    - Ampere's Law

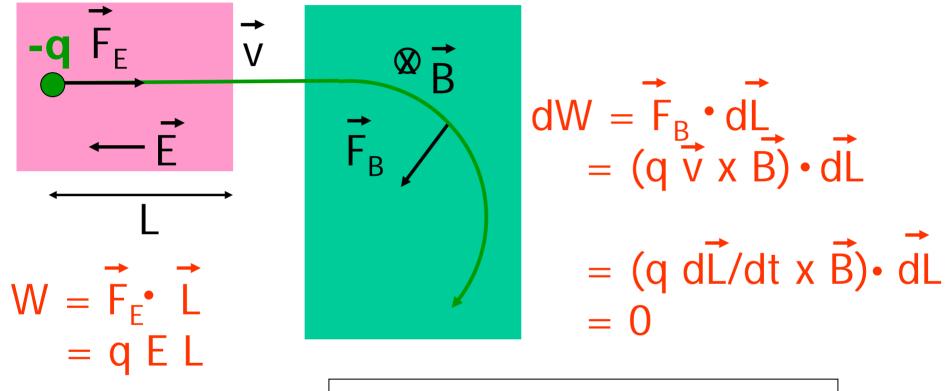
### Force on moving charge



Cyclotron Radius

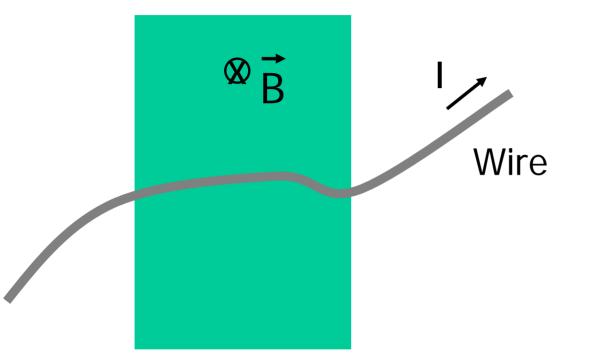
Apr 5 2002

## Work done on moving charge



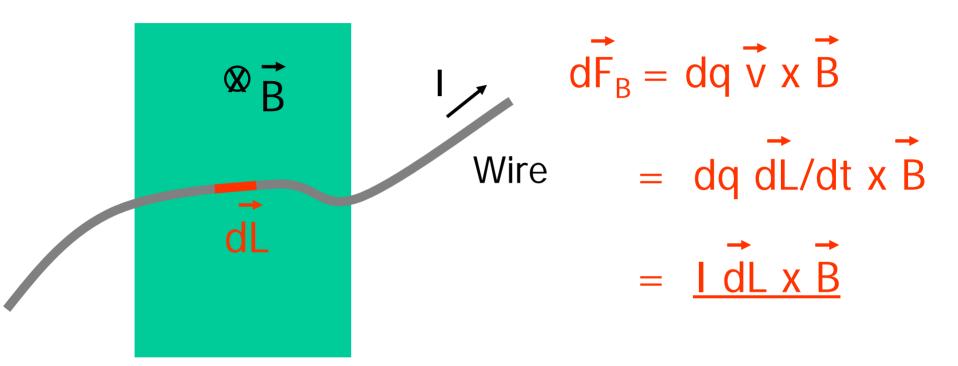
Magnetic Field does no Work!

# Force on Wire carrying current I

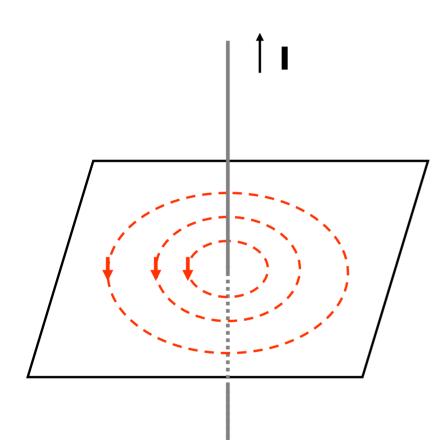


Apr 5 2002

# Force on Wire carrying current I

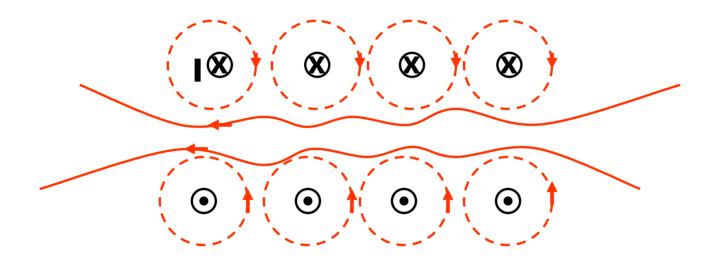


# **Currents and B-Field**

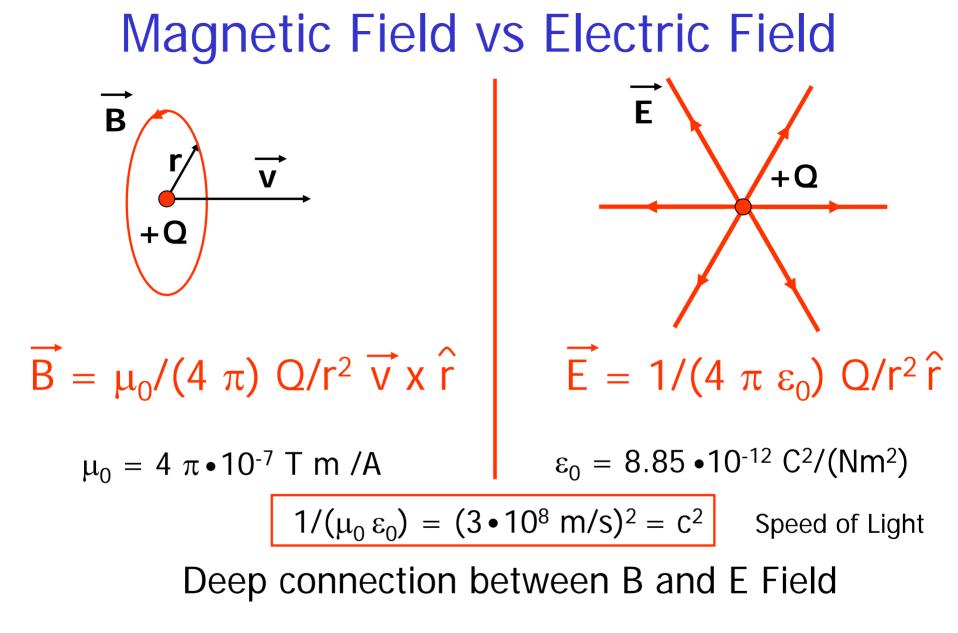


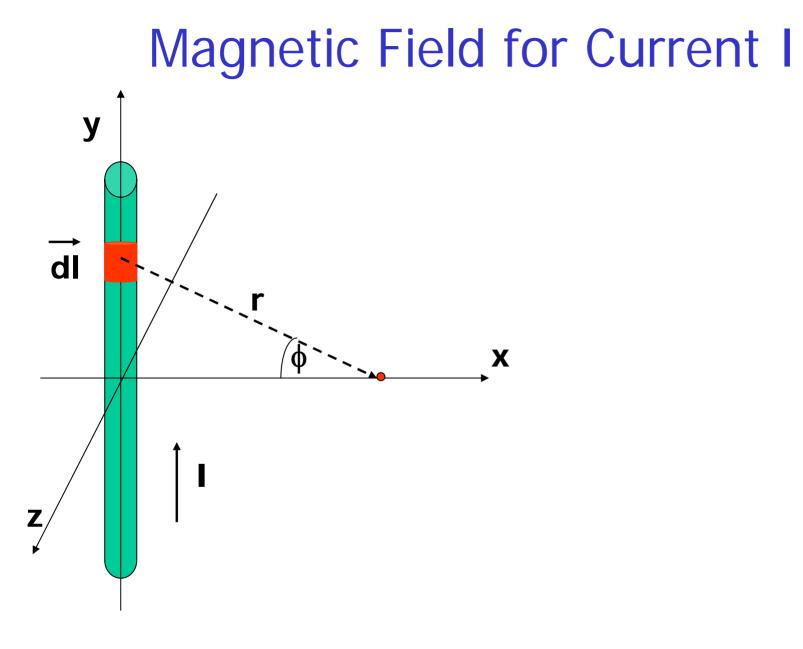
- Current as Source of B
- Magnetic Field lines are always closed
  - no Magnetic Charge (Monopole)
- Right Hand Rule

## **Currents and B-Field**



- Solenoid: Large, uniform B inside
- Superposition Principle!





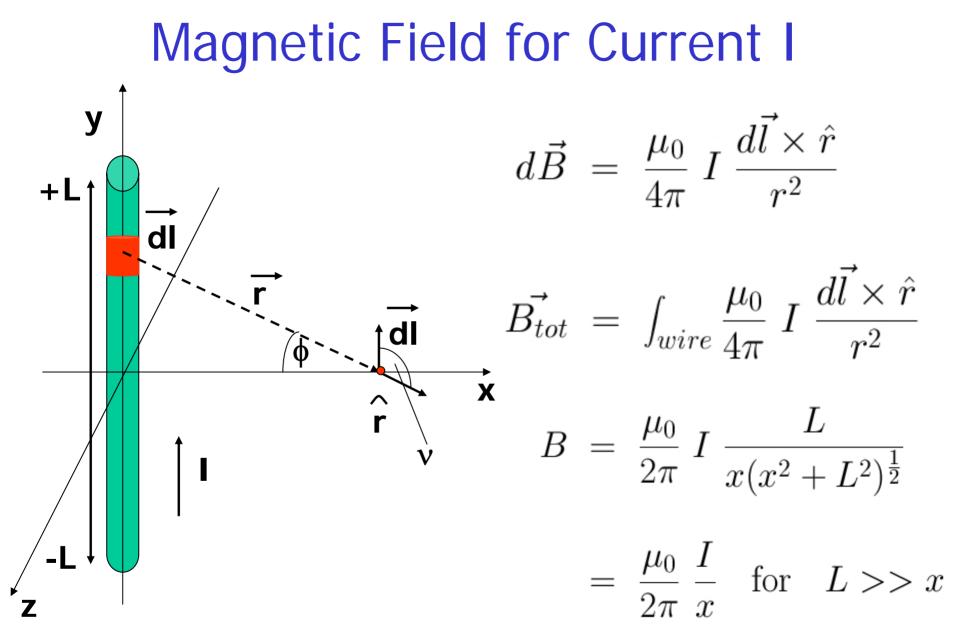
## Magnetic Field for Current I

- $dB = \mu_0/(4 \pi) dQ/r^2 \vec{v} x \hat{r}$  for charge dQ
- I = dQ/dt ->  $dQ \vec{v} = dQ dI/dt = I dI$

 $dB = \mu_0/(4 \pi) I \vec{dI} x \hat{r}/r^2$  Law of Biot-Savart

Magnetic Field dB for current through segment dl

For total B-Field: Integrate over all segments dl

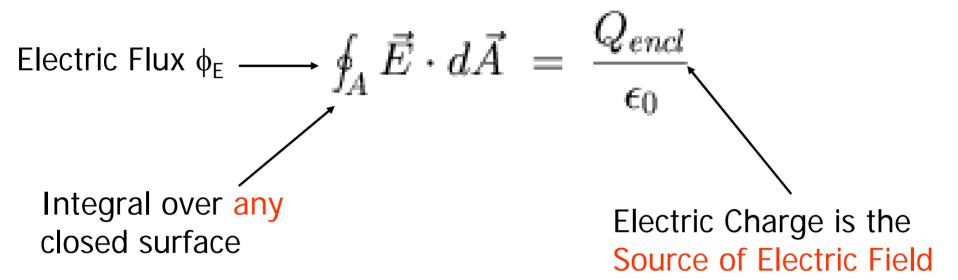


Apr 5 2002

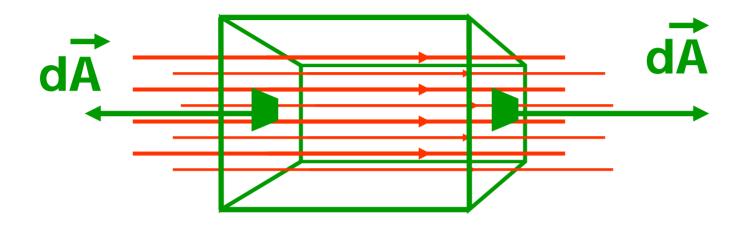
# Magnetic Field for Current I

- That was painful...
- Long calculation for such a simple case
- Is there a simpler way?
- Recall Electrostatics!

#### Remember: Gauss' Law



#### Gauss' Law



- No charge inside close surface: Flux in = -Flux out :  $\Phi = 0$
- There are no magnetic charges:
- Magnetic Flux  $\Phi_{B} = 0$  for any close surface

## Gauss' Law for Magnetic Fields

$$\Phi_B = \oint_A \vec{B} \cdot d\vec{A} = 0$$

- Magnetic Flux through closed surface is 0
- This says: There are no magnetic monopoles
- Important Law one of Maxwell's equations
- Unfortunately of limited practical use

## Ampere's Law

Ampere's idea:
Relate Field B to its Source:

-Closed Line instead of closed surface!

$$\oint_L \vec{B} \cdot d\vec{l} = \mu_0 \ I_{encl}$$

B

Î

#### Ampere's Law

Ampere's Law helps because we can choose integration path!

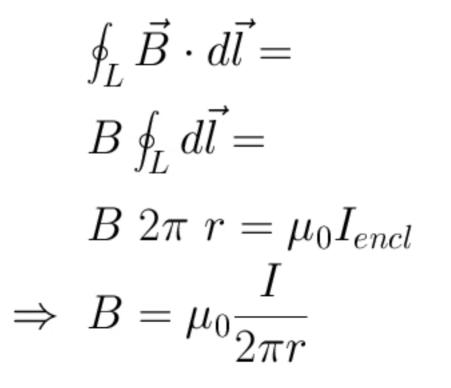
$$\vec{B} \perp d\vec{l} \Rightarrow \vec{B} \cdot d\vec{l} = 0$$
$$\vec{B} \mid \mid d\vec{l} \Rightarrow \vec{B} \cdot d\vec{l} = B \ dl$$

Right-Hand rule for relating sign of dl and l

→ B

### Ampere's Law

Ampere's Law helps because we can choose integration path!



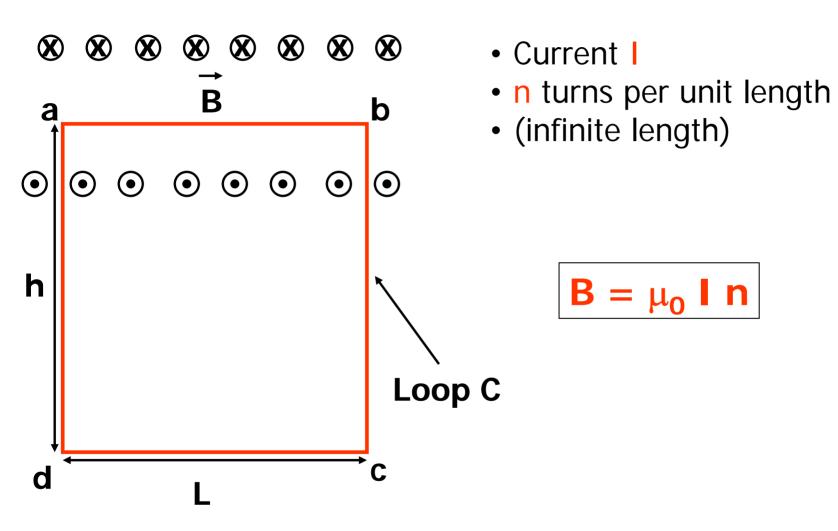
B

# Field of a Solenoid

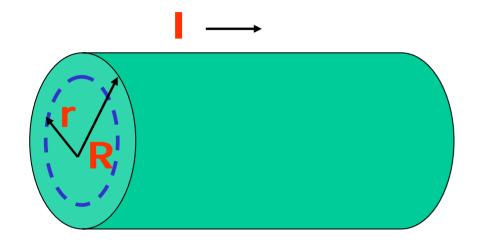
- Current
- n turns per unit length

 $\odot \odot \odot \odot \odot \odot \odot \odot$ 

## Field of a Solenoid



# **Cylindrical Conductor**



- Uniform Current-Density J
- Radius R

r

• J = I/( $\pi$  R<sup>2</sup>)

$$r < R \qquad \oint_L \vec{B} \cdot d\vec{l} = \mu_0 I_{encl}$$
$$B(r) \oint_L d\vec{l} = \mu_0 J \pi r^2$$
$$B(r) 2\pi r = \mu_0 \frac{I}{\pi R^2} \pi r^2$$
$$\Rightarrow B(r) = \mu_0 \frac{I}{2\pi R^2} r$$

$$> R \quad \oint_L \vec{B} \cdot d\vec{l} = \mu_0 \ I_{encl}$$
$$\Rightarrow B(r) 2\pi r = \mu_0 \ I$$
$$\Rightarrow B(r) = \mu_0 \frac{I}{2\pi r}$$